

# HEAPS & HEAP SORT

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Problem Solving with Computers-II

C++

```
#include <iostream>
using namespace std;

int main(){
    cout<<"Hola Facebook!";
    return 0;
}
```

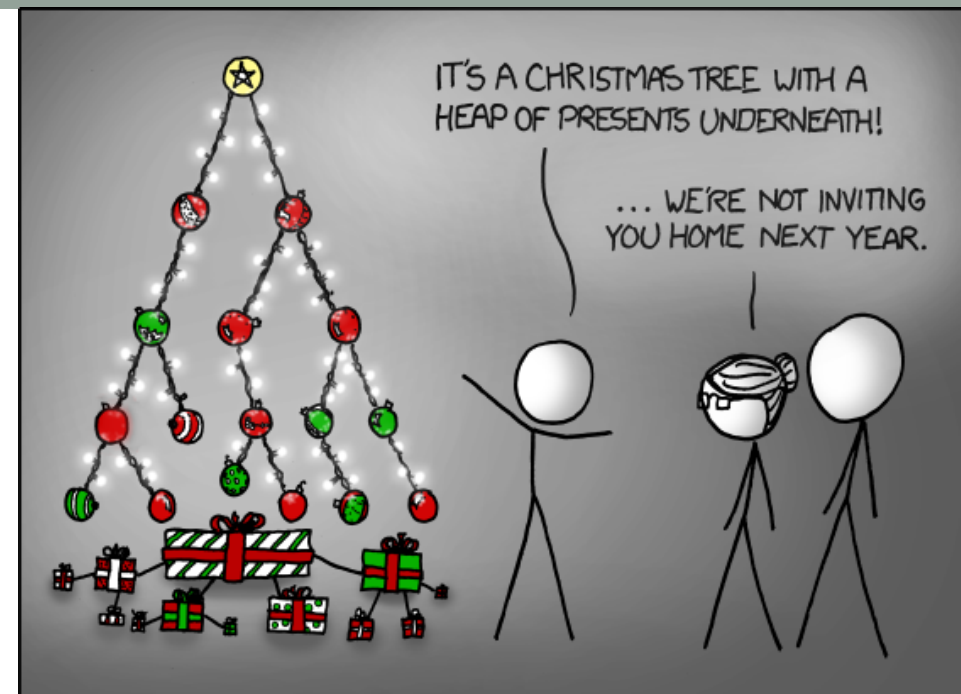


Make a copy of the handout for today's lecture:  
<https://bit.ly/CS24-Heaps-lect15>

# Review: Heap or priority\_queue

- What are the operations supported?
- What are the running times?

```
//Declare a (max) heap  
priority_queue<int> pq;
```



## Application — sorting

```
void selection_sort(vector<int>& v){
    int n = v.size();
    for (int i = 0; i < n; i++){
        int index = i;
        for (int j = i + 1; j < n; j++){
            if(v[j] > v[index]){
                index = j;
            }
        }
        if(index != i){
            int temp = v[index];
            v[index] = v[i];
            v[i] = temp;
        }
    }
}
```

**Running time:  $O(n^2)$**

**Space complexity:  $O(1)$**

**Can we do better?**

## Application — simple heap sort

```
void simple_heap_sort(vector<int>& v){
    priority_queue<int> pq;
    for(auto& elem : v){
        pq.push(elem);
    }
    int i = 0;
    while(!pq.empty()){
        v[i] = pq.top();
        pq.pop();
        i++;
    }
}
```

**Running time:**

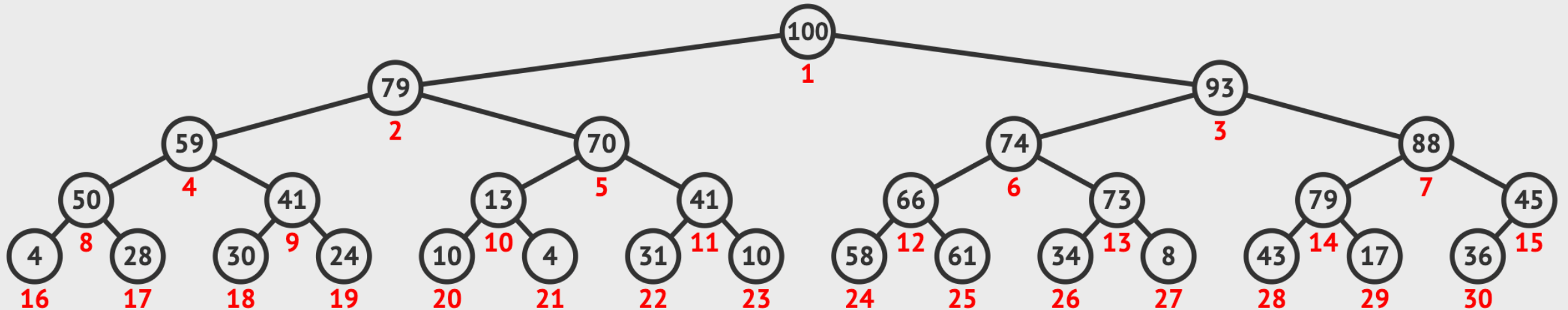
**Space complexity:**

**Can we do better?**

# Review: Two important properties of a heap

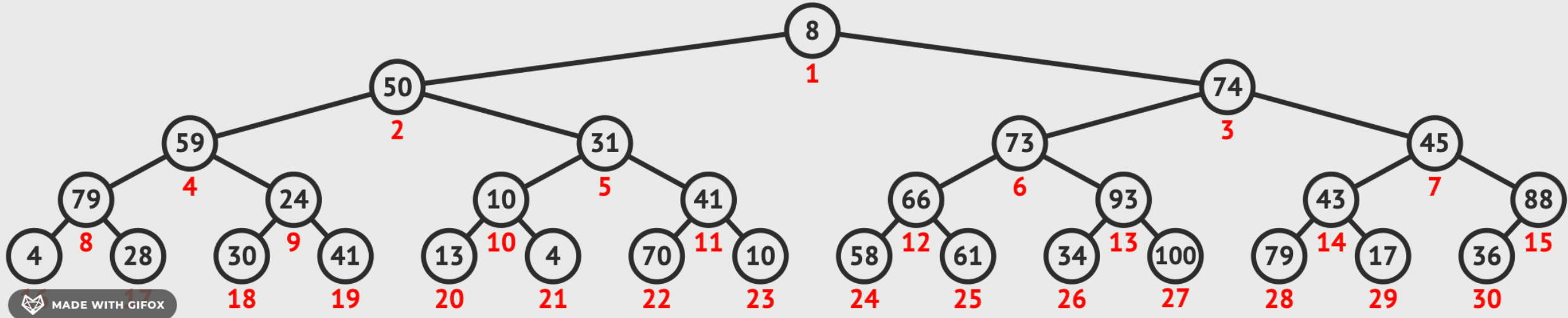
**Shape property:**

**Heap property :**





# Heapify: A fast way to turn an arbitrary vector into a heap

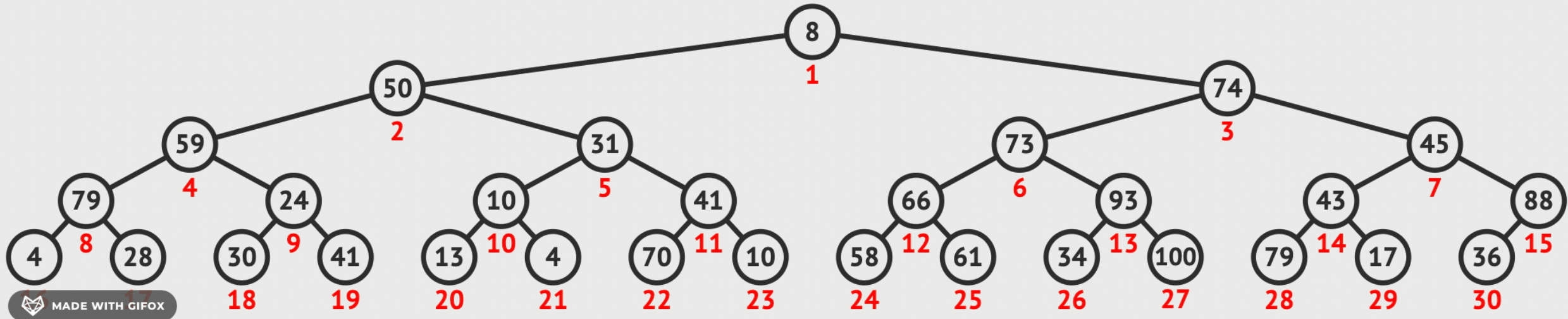


**Activity 2 (5 mins):** Observe the visualization of heapify, then describe the algorithm in your own words

To recreate the visualization, go to: <https://visualgo.net/en/heap>



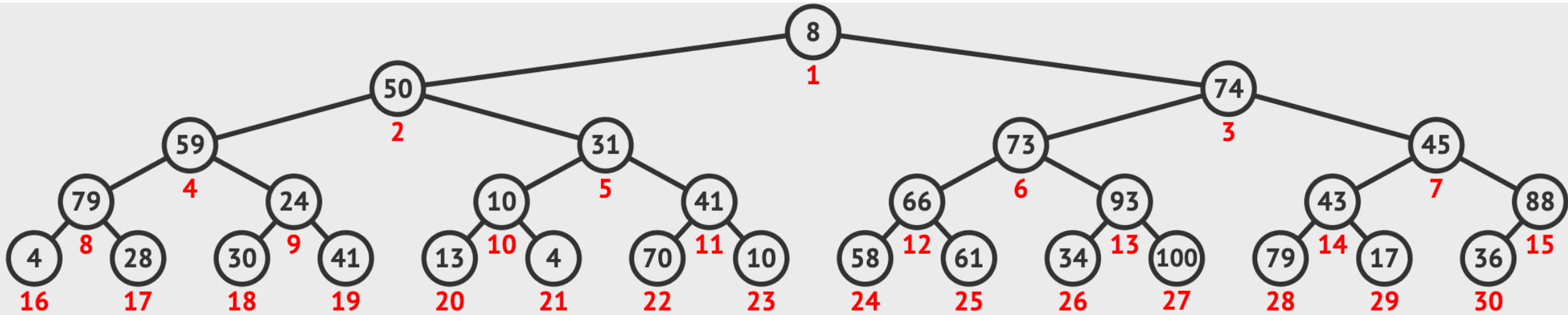
# Heapify: A fast way to turn an arbitrary vector to a heap



**High-level approach:** Given an arbitrary vector of keys. Starting from the internal node with the largest index in the vector, and moving upwards in the tree through all the internal nodes (level by level), sift the root of each subtree downward as in the **bubble-down process** until the **heap property** is restored.



# Internally the “heap binary tree” is really just a vector!



What is the largest index of an internal node in a heap with  $n$  elements?

- A.  $\log n$
- B.  $(n - 1) / 2$
- C.  $n - 1$
- D.  $n/2 - 1$
- E. None of the above

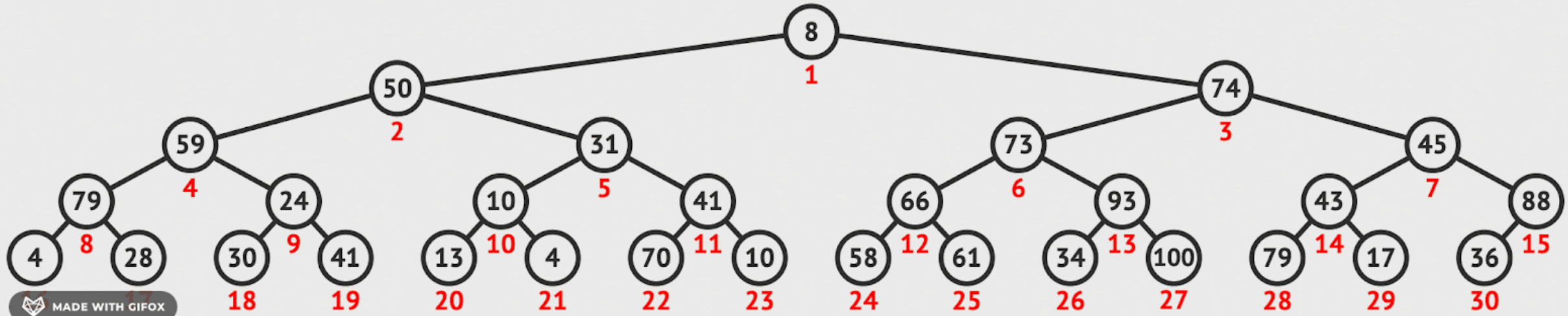
**Heapify the vector below to convert it into a max-heap (3 min)**

1	5	3	6	4	1	7	8	4
---	---	---	---	---	---	---	---	---

**What is the resulting vector?**

- A. 8 7 6 5 4 4 3 1 1
- B. 8 1 7 5 4 1 3 6 4
- C. 8 6 7 5 4 1 3 1 4
- D. Something else

# Activity 3: Running time of heapify (10 min)



# Heap Sort Algorithm

1	5	3	6	4	1	7	8	4
---	---	---	---	---	---	---	---	---

- Step 1: Heapify the input vector with  $n$  keys
- Step 2: Let  $S$  be the number of keys in the heap. Extract the max element (root key) by swapping it with the last key in the vector. Reduce the size of the heap by 1. At this point, the first  $(S - 1)$  keys in the vector represent the heap and the remaining are the sorted portion of the vector. Finally, restore the heap property of the root using the bubble down process
- Repeat step 2 while the size of the heap is greater than 1.

## std::priority\_queue template arguments

```
template <
    class T,
    class Container= vector<T>,
    class Compare = less <T>
> class priority_queue;
```

The template for priority\_queue takes 3 arguments:

1. Type elements contained in the queue.
2. Container class used as the internal store for the priority\_queue, the default is **vector<T>**
3. Class that provides priority comparisons, the default is **less**

## Comparison class: A class for comparing objects

```
class myCompare{  
    bool operator()(int& a, int & b) const {  
        return a > b;  
    }  
};
```

```
int main(){  
    myCompare cmp;  
    cout<<cmp(20, 10)<<endl;  
}
```

If `cmp(x, y)` returns true, priority queue will interpret this as:

x has \_\_\_\_\_ priority than y

Which element will be at the top of such a priority queue?



## std::priority\_queue template arguments

**//Template parameters for a max-heap**

```
priority_queue<int, vector<int>, std::less<int>> pq;
```

**//Template parameters for a min-heap**

```
priority_queue<int, vector<int>, std::greater<int>> pq;
```