

RUNNING TIME ANALYSIS OF BINARY SEARCH TREES

Problem Solving with Computers-II

The image shows the C++ logo in blue, followed by a snippet of C++ code in a monospaced font. The code is:

```
#include <iostream>
using namespace std;
int main(){
    cout<<"Hola Facebook\n";
    return 0;
}
```

What is the Big O of sumArray2

- A. $O(N^2)$
- B. $O(N)$
- C. $O(N/2)$
- D. $O(\log N)$
- E. None of the array

```
/* N is the length of the array*/  
int sumArray2(int arr[], int N)  
{  
    int result=0;  
    for(int i=1; i < N; i=i*2)  
        result+=arr[i];  
    return result;  
}
```

Running time of operations on sorted arrays: Discuss best case, worst case, average case

- Min :
- Max:
- Median:
- Successor:
- Predecessor:
- Search:
- Insert :
- Delete:

Binary Search Trees

- WHAT are the operations supported?
- HOW do we implement them?
- WHAT are the (worst case) running times of each operation?

Visualize BST operations: <https://visualgo.net/bn/bst>

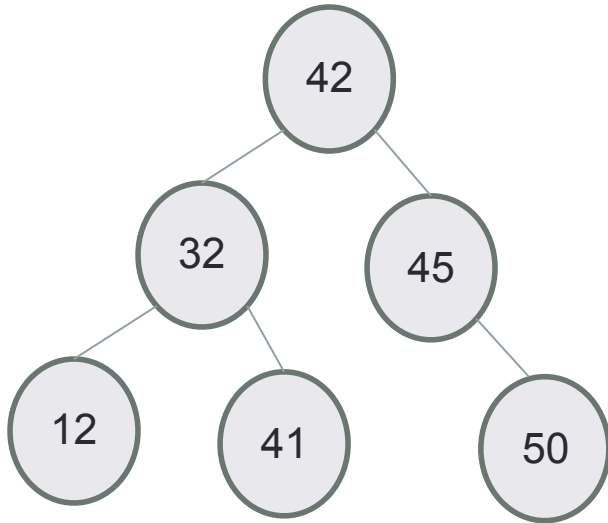
Height of the tree



Many different BSTs are possible for the same set of keys
Examples for keys: 12, 32, 41, 42, 45

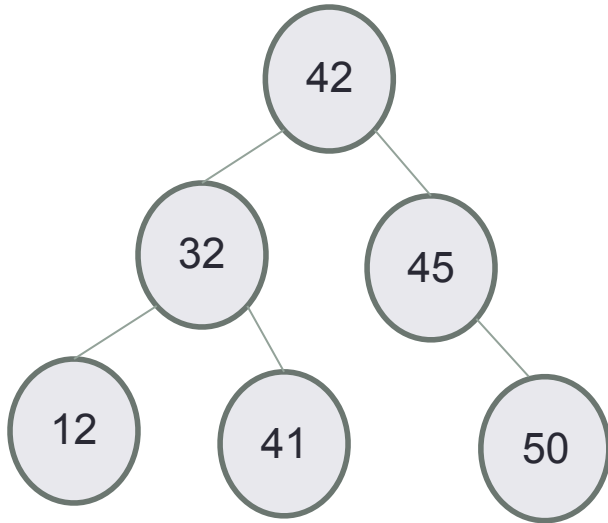
- Path – a sequence of nodes and edges connecting a node with a descendant.
- A path starts from a node and ends at another node or a leaf
- Height of node – The height of a node is the number of edges on the longest downward path between that node and a leaf.

Worst case Big-O of search



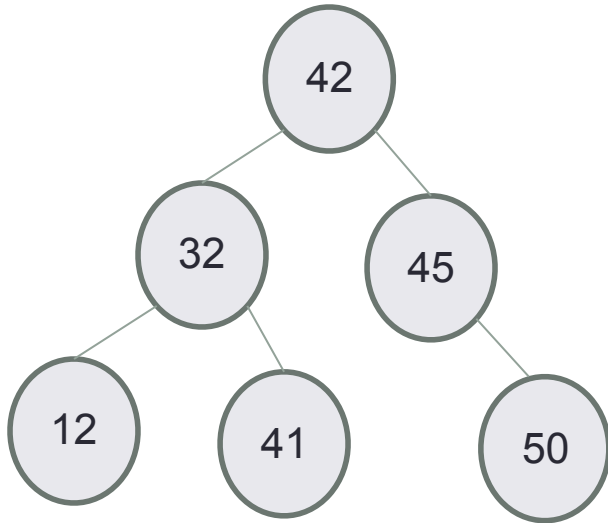
- Given a BST of height H and N nodes, what is the worst case complexity of searching for a key?
- $O(1)$
 - $O(\log N)$
 - $O(H)$
 - $O(\log H)$

Worst case Big-O of insert



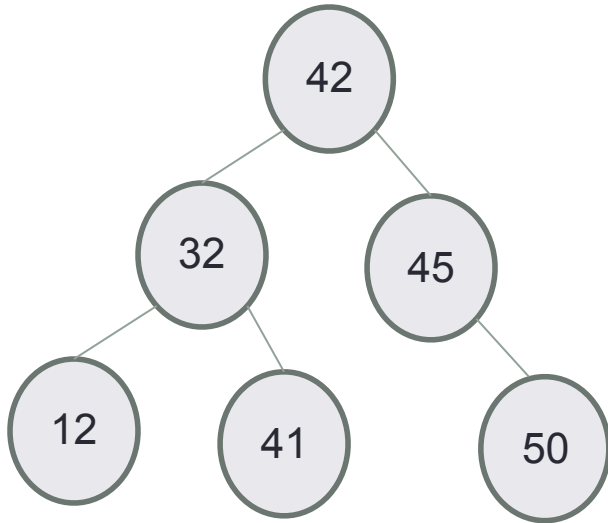
- Given a BST of height H and N nodes, what is the worst case complexity of inserting a key?
- $O(1)$
 - $O(\log N)$
 - $O(H)$
 - $O(\log H)$

Worst case Big-O of min/max



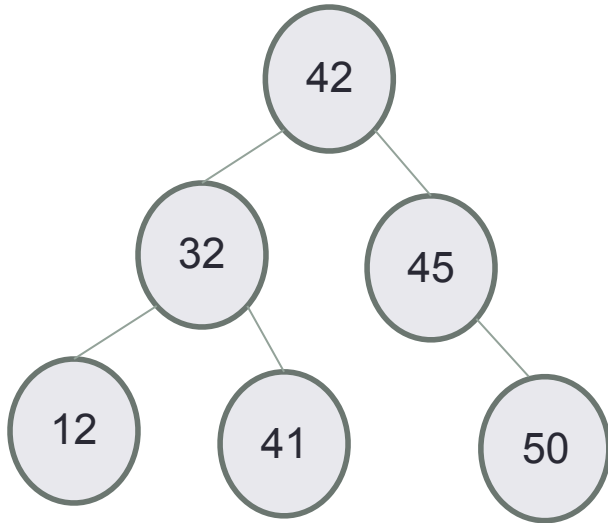
- Given a BST of height H and N nodes, what is the worst case complexity of finding the minimum or maximum key?
- $O(1)$
 - $O(\log N)$
 - $O(H)$
 - $O(\log H)$

Worst case Big-O of predecessor/successor



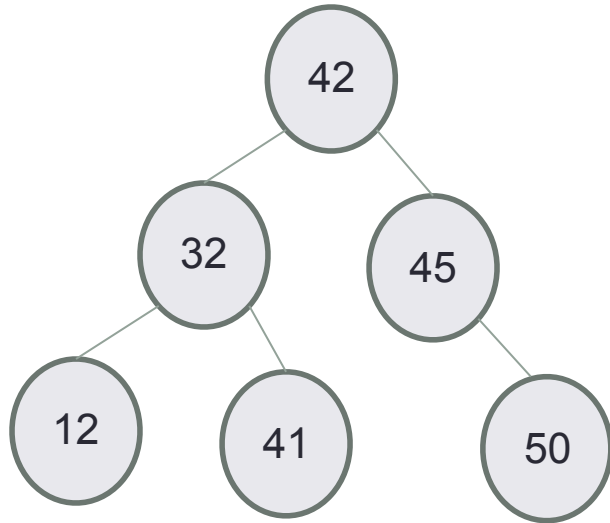
- Given a BST of height H and N nodes, what is the worst case complexity of finding the minimum or maximum key?
 - A. $O(1)$
 - B. $O(\log N)$
 - C. $O(H)$
 - D. $O(\log H)$

Worst case Big-O of delete



- Given a BST of height H and N nodes, what is the worst case complexity of deleting the key (assume no duplicates)?
 - A. $O(1)$
 - B. $O(\log N)$
 - C. $O(H)$
 - D. $O(\log H)$

Big O of traversals



In Order:

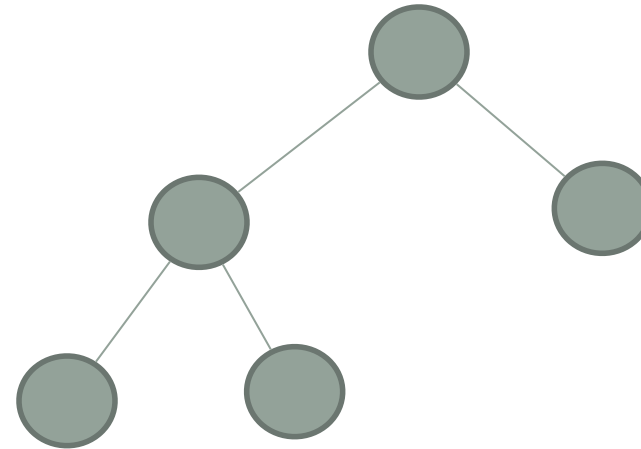
Pre Order:

Post Order:

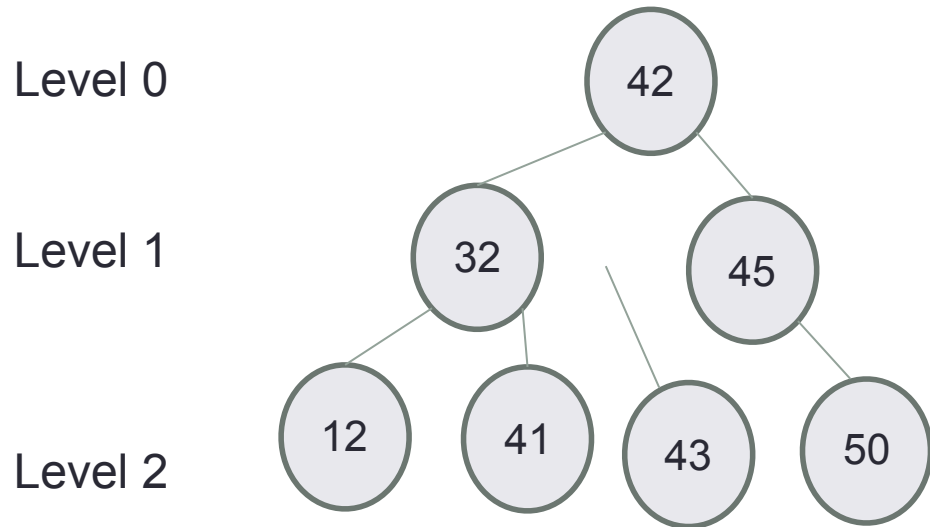
Worst case analysis

Are binary search trees *really* faster than linked lists for finding elements?

- A. Yes
- B. No

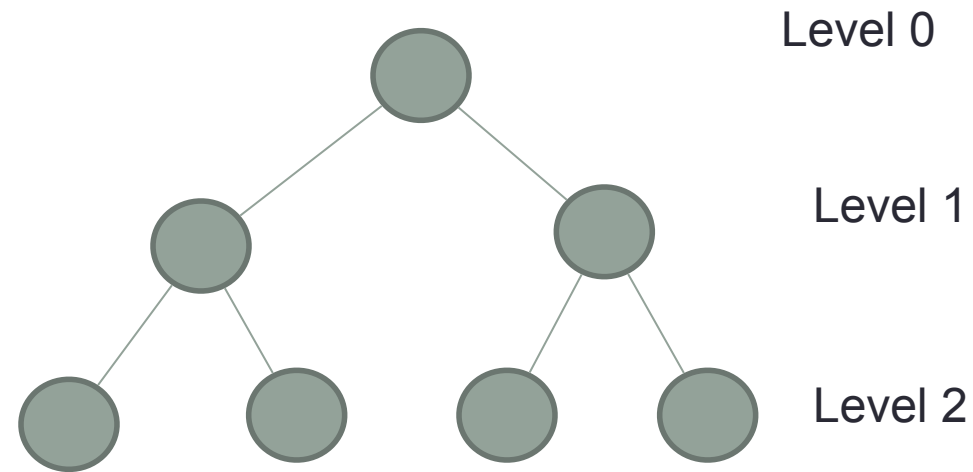


Completely filled binary tree



Nodes at each level have exactly two children, except the nodes at the last level

Relating H (height) and N (#nodes)
find is $O(H)$, we want to find a $f(N) = H$



How many nodes are on level L in a completely filled binary search tree?

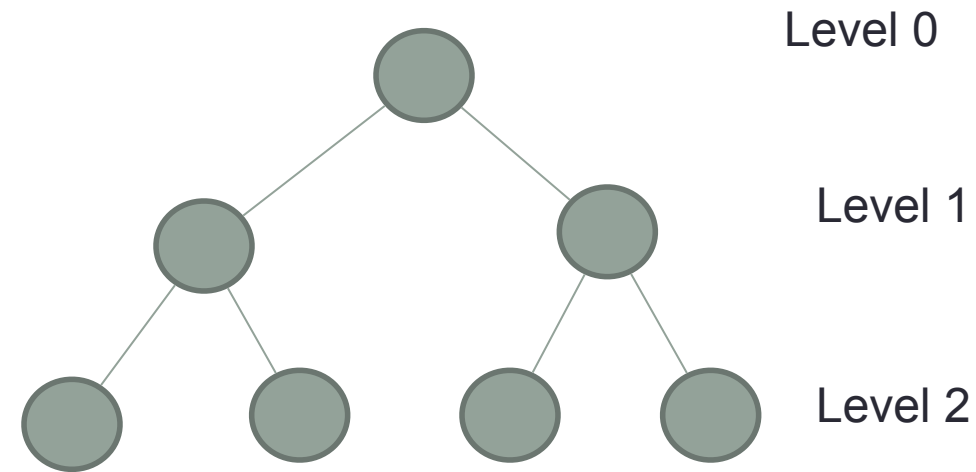
A.2

B.L

C. 2^L

D. 2^L

Relating H (height) and N (#nodes)
find is $O(H)$, we want to find a $f(N) = H$



Finally, what is the height (exactly) of the tree in terms of N ?
...

Balanced trees

- Balanced trees by definition have a height of $O(\log N)$
- A completely filled tree is one example of a balanced tree
- Other Balanced BSTs include AVL trees, red black trees and so on
- Visualize operations on an AVL tree: <https://visualgo.net/bn/bst>

Summary of operations

Operation	Sorted Array	Binary Search Tree	Linked List
Min			
Max			
Median			
Successor			
Predecessor			
Search			
Insert			
Delete			

CHANGING GEARS: C++STL

- The C++ Standard Template Library is a very handy set of three built-in components:
 - Containers: Data structures
 - Iterators: Standard way to search containers
 - Algorithms: These are what we ultimately use to solve problems

C++ STL container classes

```
array
vector
forward_list
list
stack
queue
priority_queue
set
multiset (non unique keys)
deque
unordered_set
map
unordered_map
multimap
bitset
```