

HEAPS

Problem Solving with Computers-II

C++

```
#include <iostream>
using namespace std;

int main(){
    cout<<"Hola Facebook\n";
    return 0;
}
```



How is PA02 going?

- A. Done
- B. On track to finish
- C. Having some difficulties
- D. Just started
- E. Haven't started

Heaps

- Clarification
 - *heap*, the data structure is not related to *heap*, the region of memory
- Key questions:
 - What are the operations supported?
 - What are the running times?

Operations:

min or max

$O(1)$

insert

$O(\log N)$

delete

$O(\log N)$

Heaps

- Insert :
- Min:
- Delete Min:
- Max
- Delete Max

Min-Heaps

$O(\log N)$

$O(1)$

$O(\log N)$

—

—

Max-Heap

$O(\log N)$

—

—

$O(1)$

$O(\log N)$

(Balanced)

BST

$O(\log N)$

—

$O(\log N)$

$O(\log N)$

Applications:

- Efficient sort
- Finding the median of a sequence of numbers
- Compression codes

Choose heap if you are doing repeated insert/delete/(min OR max) operations

std::priority_queue (STL's version of heap)

A C++ `priority_queue` is a generic container, and can store any data type on which an ordering can be defined: for example ints, structs (Card), pointers etc.

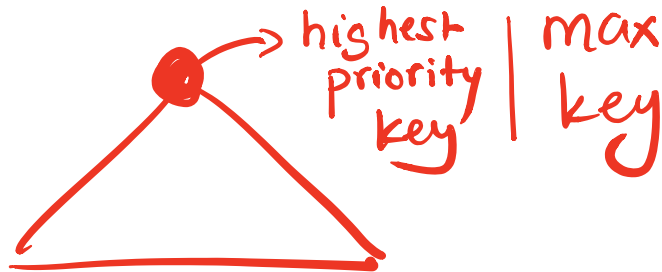
```
#include <queue>
priority_queue<int> pq;
```

type of keys (pointing to `int`)

heap object (pointing to `pq`)

Methods:

```
* push()    //insert
* pop()     //delete max priority item
* top()     //get max priority item
* empty()   //returns true if the priority queue is empty
```



- You can extract object of highest priority in $O(\log N)$
- To determine priority: objects in a priority queue must be comparable to each other

STL Heap implementation: Priority Queues in C++

What is the output of this code?

```
priority_queue<int> pq;  
pq.push(10);  
pq.push(2);  
pq.push(80);  
cout<<pq.top();  
pq.pop();  
cout<<pq.top();  
pq.pop();  
cout<<pq.top();  
pq.pop();
```



80 10 2

A. 10 2 80

B. 2 10 80

☒ C. 80 10 2

D. 80 2 10

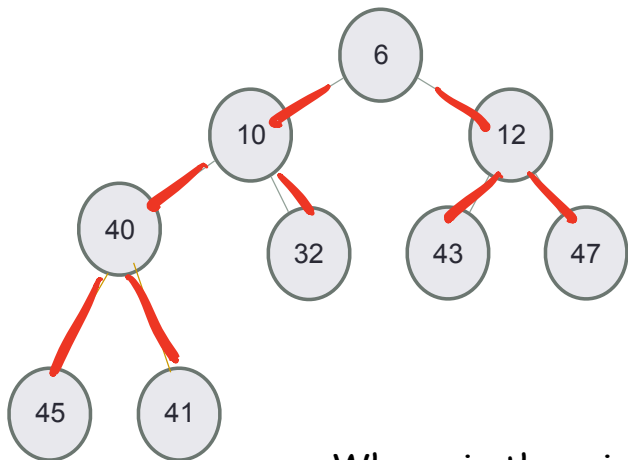
E. None of the above

Heaps as binary trees

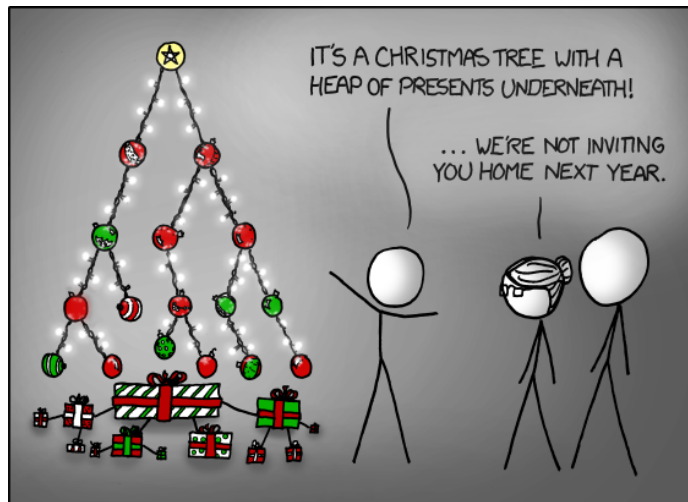
- Rooted binary tree that is as complete as possible
- In a **min-Heap**, each node satisfies the following **heap property**:

$$\text{key}(x) \leq \text{key}(\text{children of } x)$$

Min Heap with 9 nodes

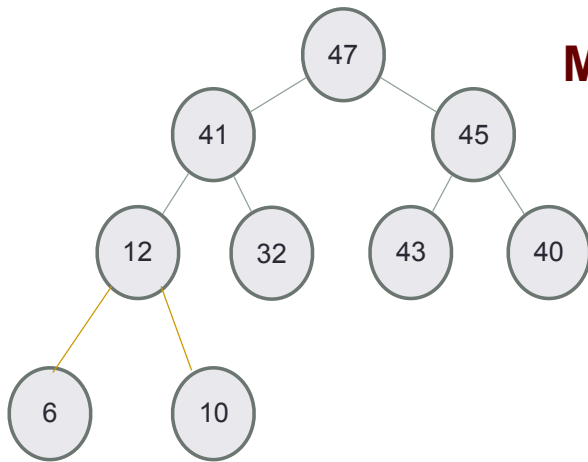


Where is the minimum element?



Heaps as binary trees

- Rooted binary tree that is as complete as possible
- In a max-Heap, each node satisfies the following **heap property**:
 $\text{key}(x) \geq \text{key}(\text{children of } x)$



Max Heap with 9 nodes

Where is the maximum element?

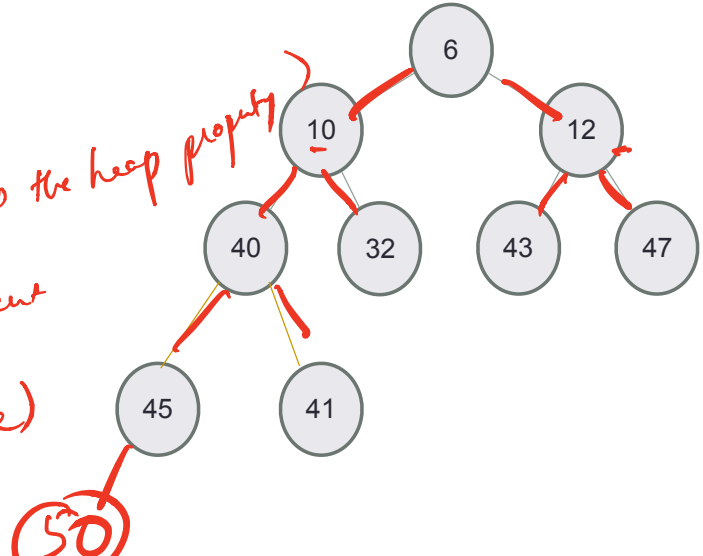
Identifying heaps

Starting with the following min-Heap which of the following operations will result in something that is NOT a min Heap

- A. Swap the nodes 40 and 32
- B. Swap the nodes 32 and 43
- C. Swap the nodes 43 and 40
- D. Insert 50 as the left child of 45

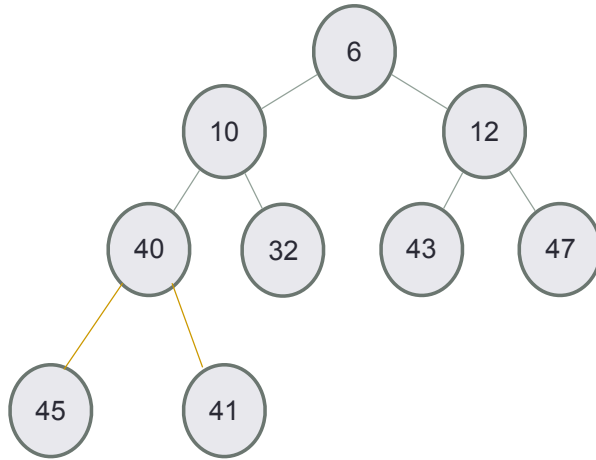
E. C&D

(Violates the requirement that the heap should be a complete tree)



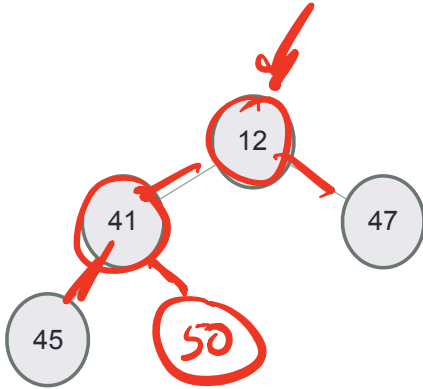
Structure: Complete binary tree

A heap is a complete binary tree: Each level is as full as possible. Nodes on the bottom level are placed as far left as possible

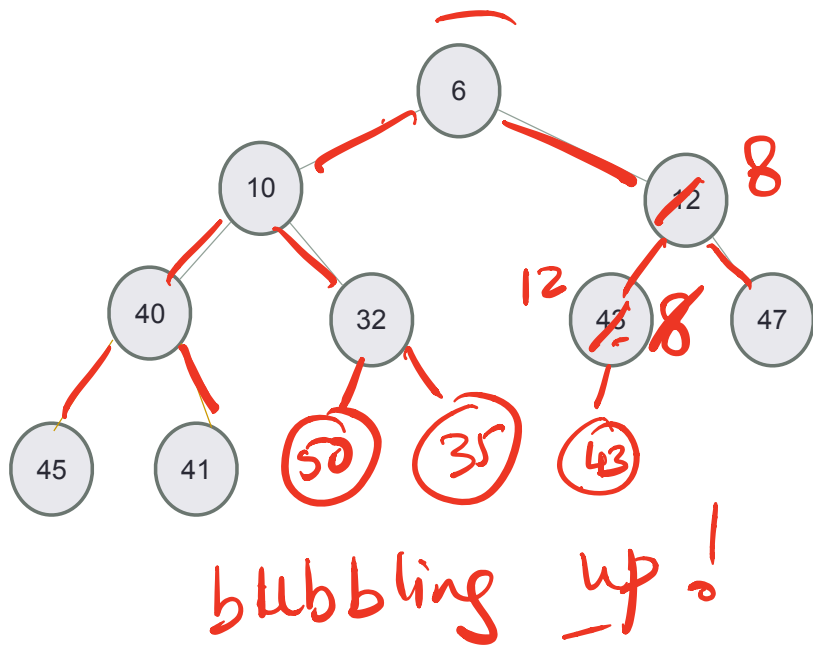


Insert 50 into a heap

- Insert key(x) in the first open slot at the last level of tree (going from left to right)
- If the heap property is not violated - Done
- Else: while($\text{key}(\text{parent}(x)) > \text{key}(x)$) swap the key(x) with key(parent(x))

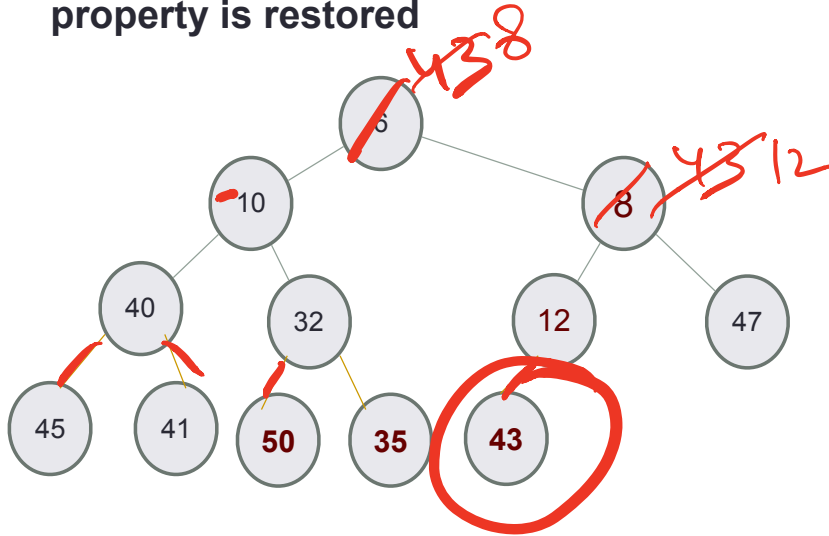


Insert 50, then 35, then 8



Delete min

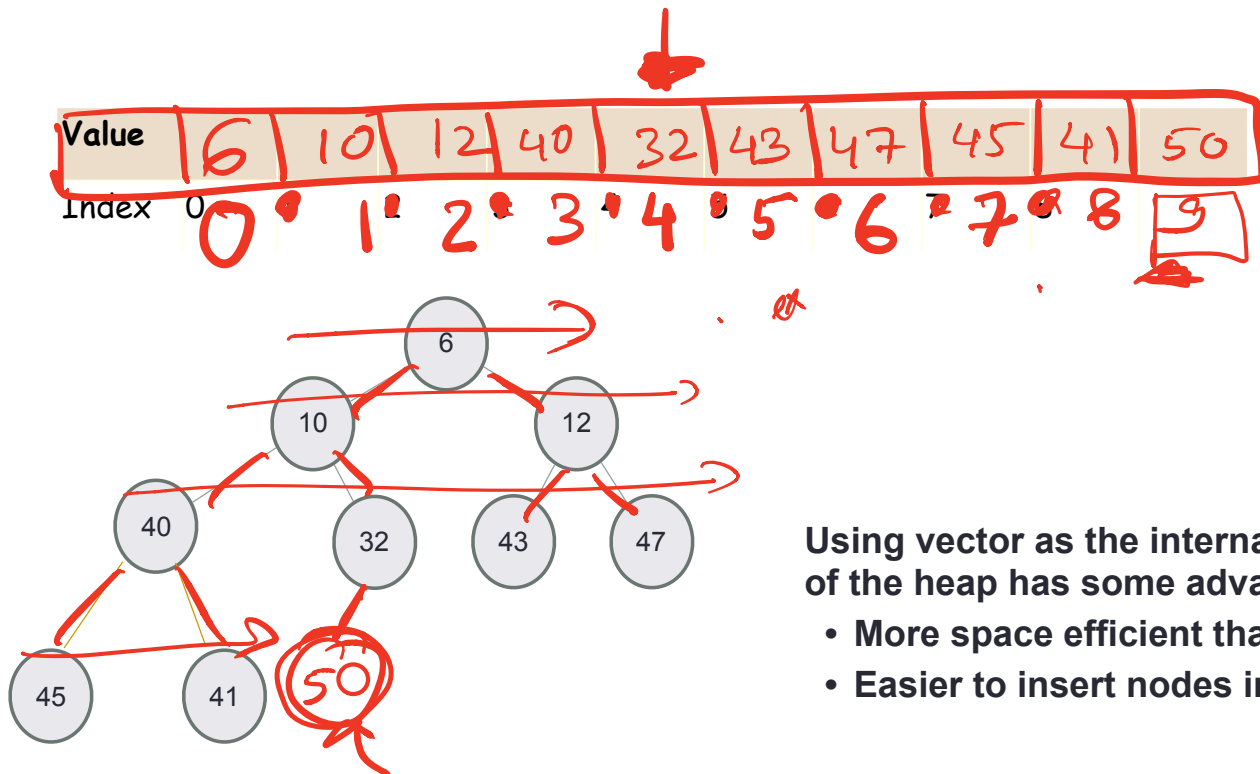
- Replace the root with the rightmost node at the last level
- “Bubble down”- swap node with one of the children until the heap property is restored



Under the hood of heaps

- An efficient way of implementing heaps is using vectors
- Although we think of heaps as trees, the entire tree can be efficiently represented as a vector!!

Implementing heaps using an array or vector



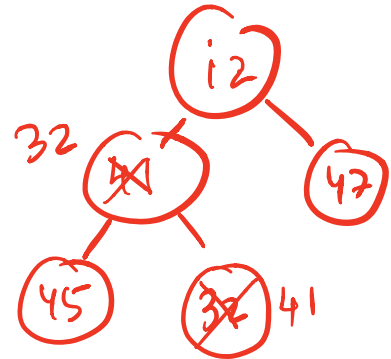
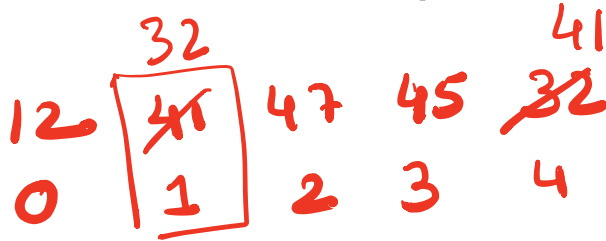
Using vector as the internal data structure of the heap has some advantages:

- **More space efficient than trees**
- **Easier to insert nodes into the heap**

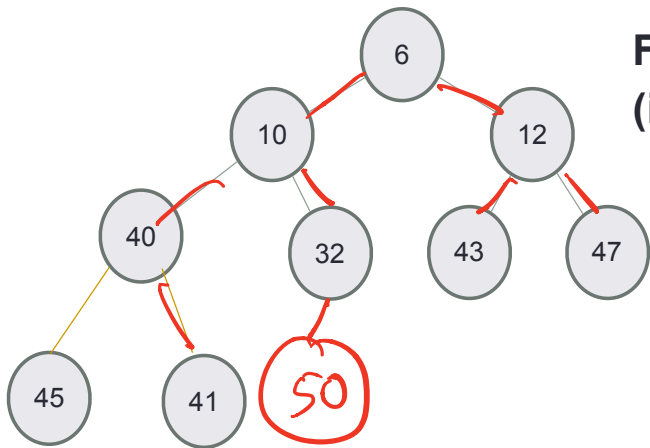
Insert into a heap

- Insert key(x) in the first open slot at the last level of tree (going from left to right)
- If the heap property is not violated - Done
- Else....

Insert the elements {12, 41, 47, 45, 32} in a min-Heap using the vector representation of the heap



Finding the “parent” of a “node” in the vector representation



For a node at index i , index of the parent is $(i-1)/2$

For node at index i ,

$$\text{Parent}(i) = \frac{(i-1)}{2}$$

$$\text{leftchild}(i) = 2i + 1$$

$$\text{Rightchild}(i) = 2i + 2$$

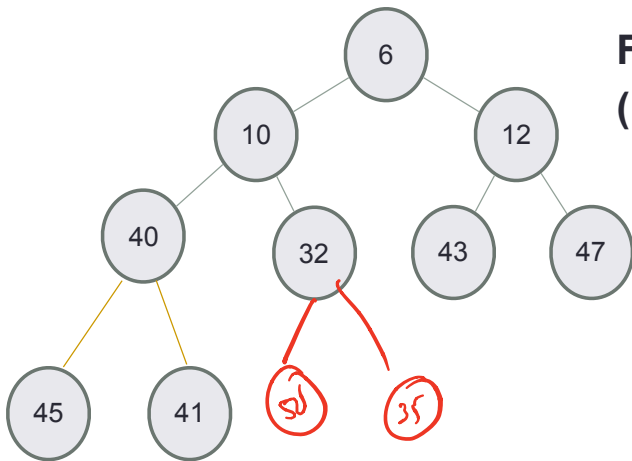
Value	6	<u>10</u>	<u>12</u>	40	<u>32</u>	43	47	45	41	50
-------	---	-----------	-----------	----	-----------	----	----	----	----	----

Index	0	1	2	3	4	5	6	7	8	9
-------	---	---	---	---	---	---	---	---	---	---

Index
Parent

-1	0	0	1	1	2	2	3	3	4
----	---	---	---	---	---	---	---	---	---

Insert 50, then 35



For a node at index i , index of the parent is $(i-1)/2$

Value	6	10	12	40	32	43	47	45	41	50	35
Index	0	1	2	3	4	5	6	7	8	9	10

Insert 8 into a heap

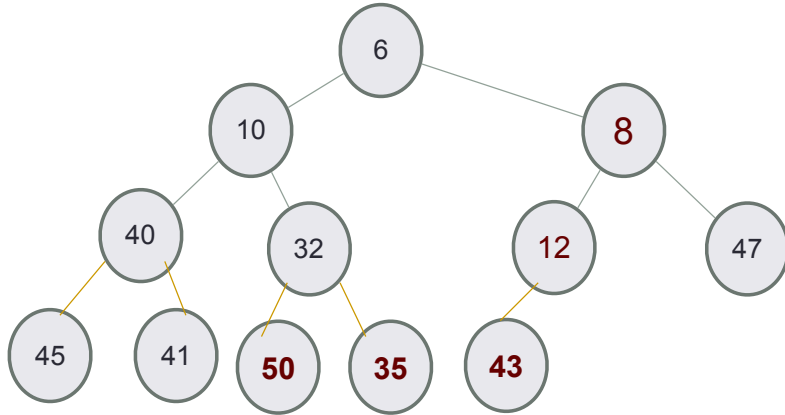
Value	6	10	12 ⁸	40	32	43 ¹²	47	45	41	50	35	8 ⁴³
Index	0	1	2	3	4	5	6	7	8	9	10	11

After inserting 8, which node is the parent of 8 ?

- ☒ A. Node 6
- ☐ B. Node 12
- ☐ C. None 43
- ☐ D. None - Node 8 will be the root

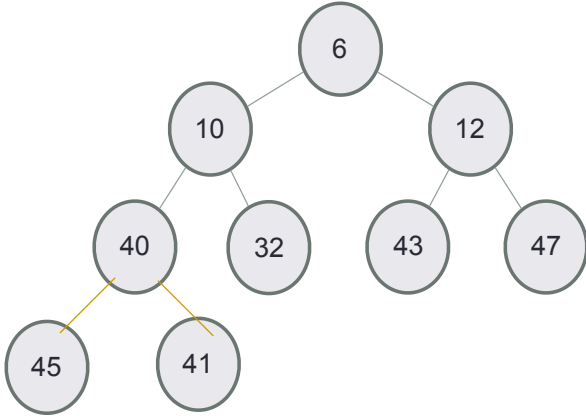
Delete min

- Replace the root with the rightmost node at the last level
- “Bubble down”- swap node with one of the children until the heap property is restored



Traversing down the tree

Value	6	10	12	40	32	43	47	45	41	
Index	0	1	2	3	4	5	6	7	8	



For a node at index i , what is the index of the left and right children?

A. $(2*i, 2*i+1)$

B. $(2*i+1, 2*i+2)$

C. $(\log(i), \log(i)+1)$

D. None of the above

Next lecture

- More on STL implementation of heaps (priority queues)
- Queues