RECURSION GDB BINARY SEARCH TREES

Problem Solving with Computers-II



```
Concept Question
LinkedList::~LinkedList(){
   delete head;
}
```

```
class Node {
    public:
        int info;
        Node *next;
};
```

Which of the following objects are deleted when the destructor of Linked-list is called? head tail

(A) 1 2 3 (B): only the first node

(C): A and B

(D): All the nodes of the linked list

(E): A and D

```
Concept question
```

```
LinkedList::~LinkedList(){
    delete head;
}
```

```
Node::~Node(){
    delete next;
}
```

Which of the following objects are deleted when the destructor of Linked-list is called? head tail

(B): All the nodes in the linked-list

(C): A and B

(D): Program crashes with a segmentation fault

(E): None of the above



Node::~Node(){
 delete next;
}



Binary Search

- Binary search. Given value and sorted array a[], find index i such that a[i] = value, or report that no such index exists.
- Invariant. Algorithm maintains a[lo] ≤ value ≤ a[hi].
- Ex. Binary search for 33.

6	13	14	25	33	43	51	53	64	72	84	93	95	96	97
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14
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GDB: GNU Debugger

- To use gdb, compile with the -g flag
- Setting breakpoints (b)
- Running programs that take arguments within gdb (r arguments)
- Continue execution until breakpoint is reached (c)
- Stepping into functions with step (s)
- Stepping over functions with next (n)
- Re-running a program (r)
- Examining local variables (info locals)
- Printing the value of variables with print (p)
- Quitting gdb (q)
- Debugging segfaults with backtrace (bt)

Demo debugging using gdb.

* Refer to the gdb cheat sheet: https://ucsb-cs24.github.io/m19/lectures/GDB-cheatsheet.pdf

Trees



A tree has following general properties:

- One node is distinguished as a **root**;
- Every node (exclude a root) is connected by a directed edge *from* exactly one other node;

A direction is: *parent -> children*

• Leaf node: Node that has no children

Which of the following is/are a tree?



Binary Search Trees

• What are the operations supported?

• What are the running times of these operations?

• How do you implement the BST i.e. operations supported by it?

Binary Search Tree – What is it?



- Each node:
 - stores a key (k)
 - has a pointer to left child, right child and parent (optional)
 - Satisfies the Search Tree Property

For any node,

Keys in node's left subtree <= Node's key Node's key < Keys in node's right subtree

Which of the following is/are a binary search tree?



BSTs allow efficient search!



- Start at the root;
- Trace down a path by comparing **k** with the key of the current node x:
 - If the keys are equal: we have found the key
 - If $\mathbf{k} < \text{key}[\mathbf{x}]$ search in the left subtree of x
 - If **k** > key[x] search in the right subtree of x



Search for 41, then search for 53

A node in a BST

class BSTNode {

public: BSTNode* left; BSTNode* right; BSTNode* parent; int const data;

```
BSTNode( const int & d ) : data(d) {
   left = right = parent = 0;
};
```

Define the BST ADT

