

# QUEUES & BREADTH-FIRST TRAVERSAL COMPLETE BINARY TREES

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Problem Solving with Computers-II

C++





```
#include <iostream>
using namespace std;

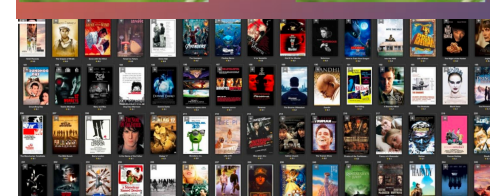
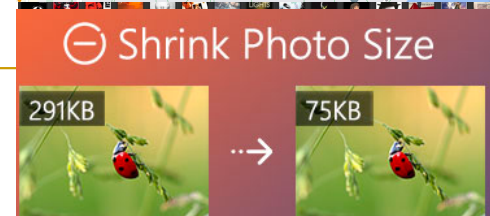
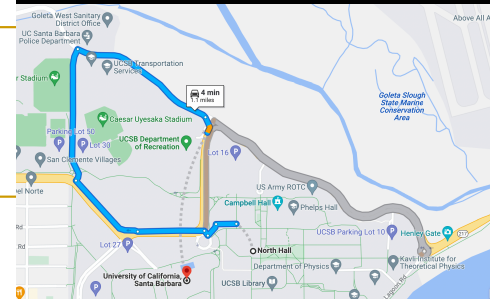
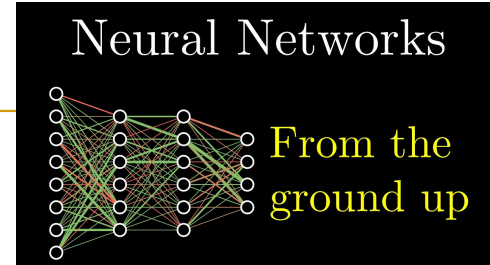
int main(){
    cout<<"Hola Facebook!n";
    return 0;
}
```



Link to handout: <https://bit.ly/CS24-Queue>

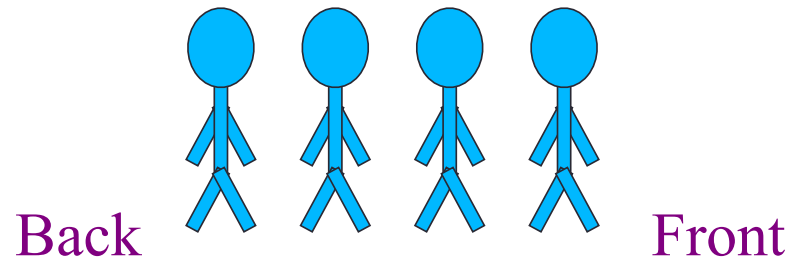
# From Data Structures to Real-World Applications

Data Structure	Algorithm	Real-World Application
Queue	Breadth-First Search (BFS)	 Machine Learning (PA03: Prediction in NNs)
Queue	Round-Robin Scheduling	 Operating Systems (Task scheduling)
Priority Queue	Dijkstra's Algorithm	 GPS Navigation (Shortest path)
Priority Queue	Huffman Coding	 Data Compression (ZIP, JPEG, MP3)
Your choice!	You design!	Querying a movie dataset (PA02)



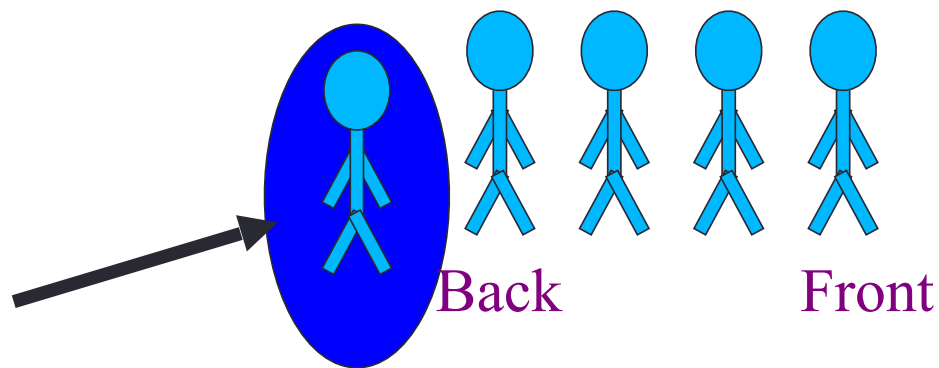
# Queue: First come First Serve

- A queue is like a queue of people waiting to be serviced
- The queue has a front and a back.



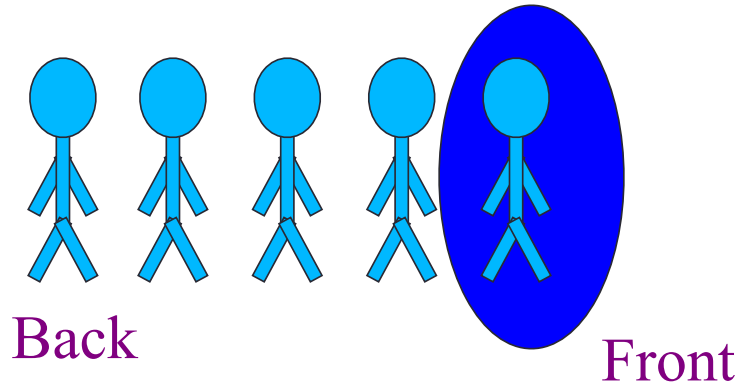
# Queue Operations: push, pop, front, back

New people must enter the queue at the back. The C++ queue class calls this a push operation.



# Queue Operations: push, pop, front, back

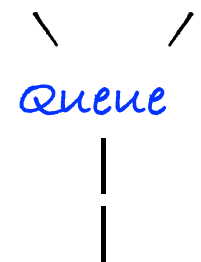
- To check the item in the front of the queue, use **front()**
- To check the item at the back of the queue, use **back()**
- When an item is taken from the queue, it always comes from the front.
- To delete an element from the front of the queue, use **pop()**



# Queue Operations: empty(), push, pop, front, back: $O(1)$

```
std::queue<int> q;  
q.empty(); //true  
q.push(1);  
// push 2, 3, 4, 5  
q.front();  
q.back();  
q.pop();
```

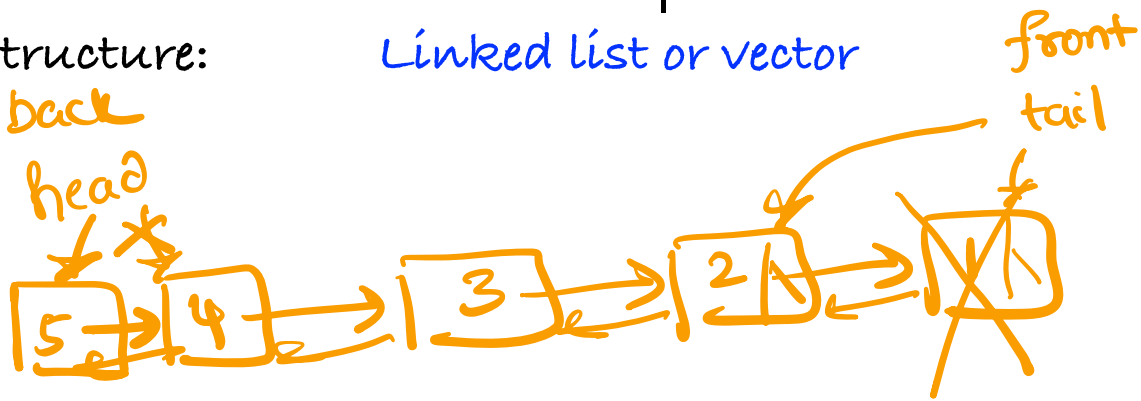
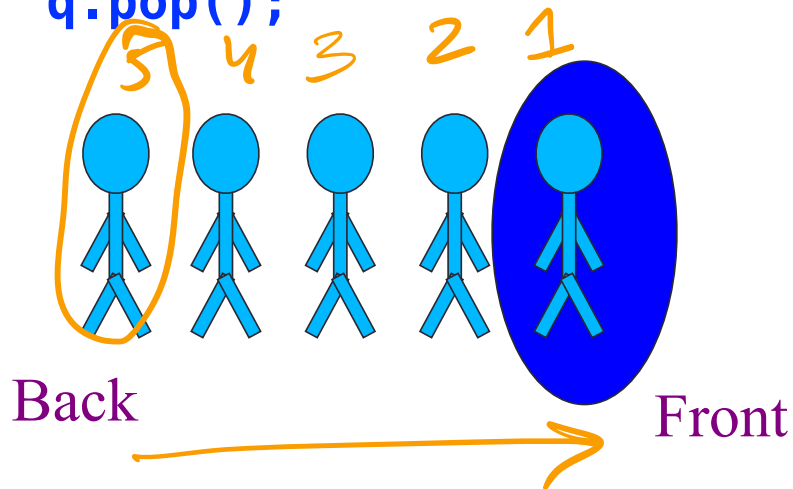
Algorithms: Breadth First Search    Task Scheduling

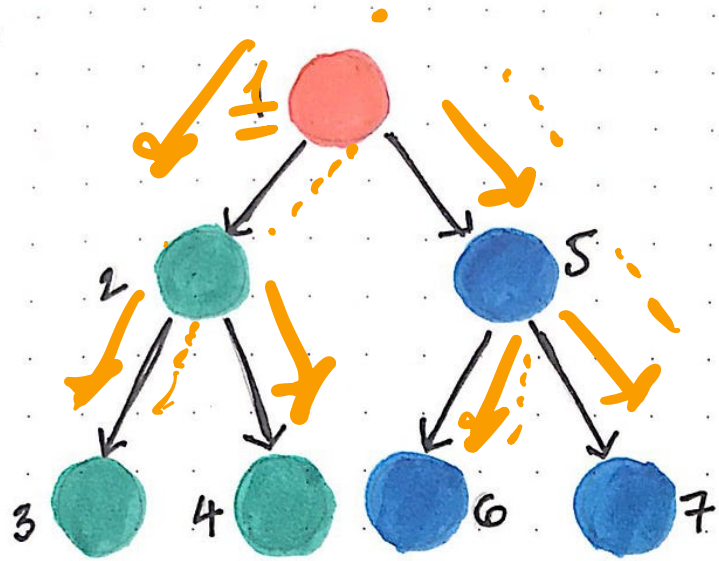


ADT:

Data structure:

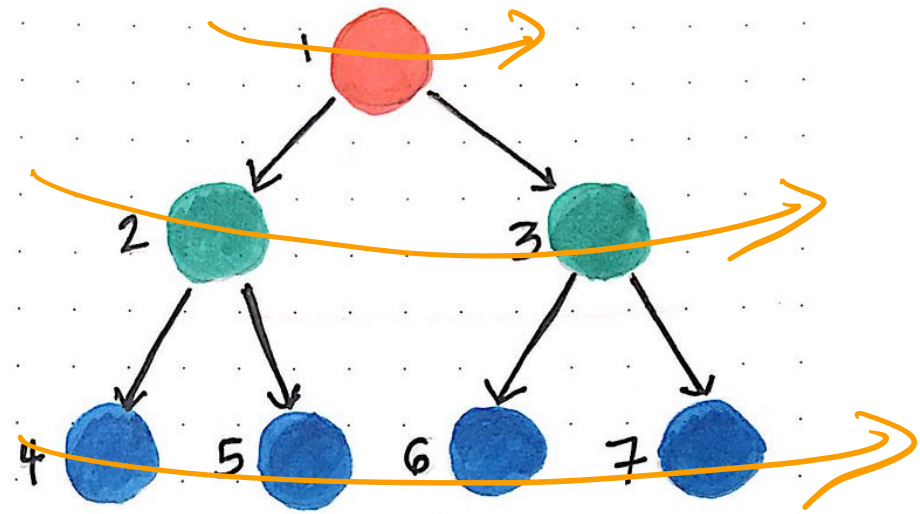
Linked list or vector





### Depth-first search

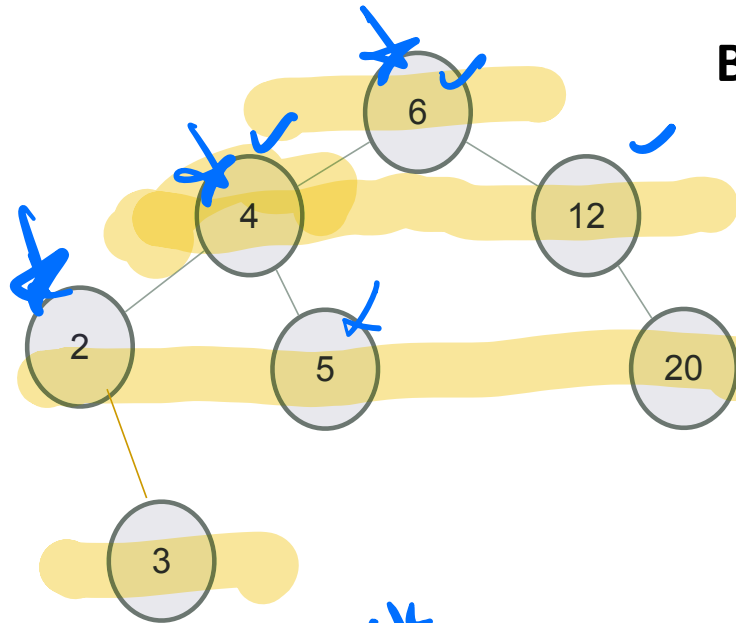
- Traverse through left subtree(s) first, then traverse through the right subtree(s).



### Breadth-first search

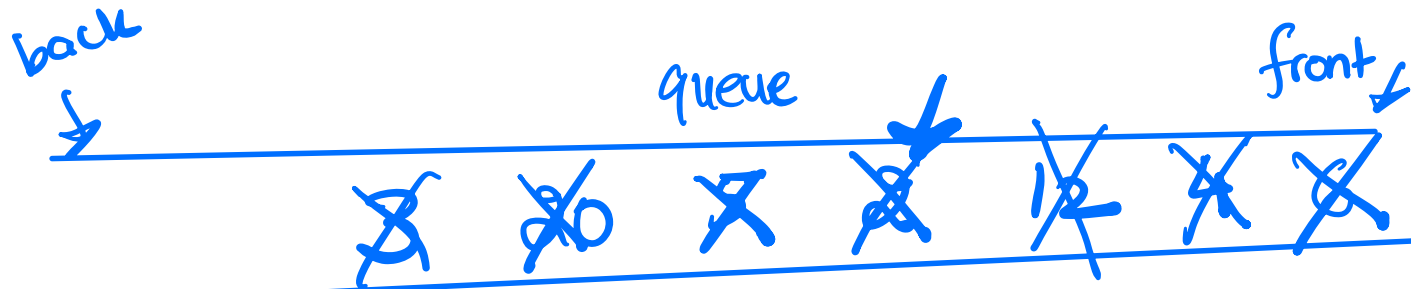
- Traverse through one level of children nodes, then traverse through the level of grandchildren nodes (and so on...).

# Breadth-first traversal/search



## BFS Algo:

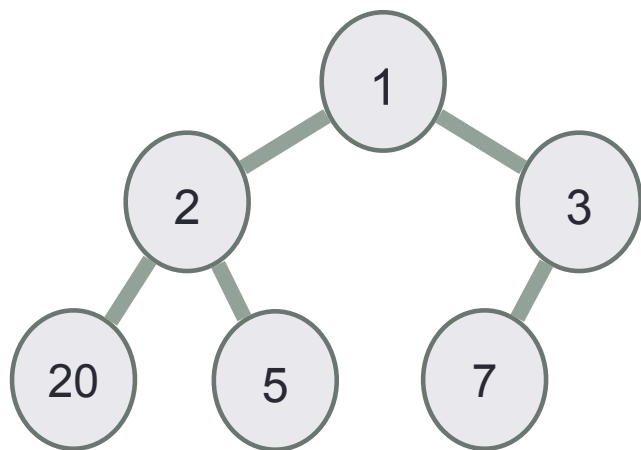
- Create an empty **queue**.
- Insert the **root** into the **queue**.
- While queue is not empty,
  - **Print** the key in the front of the queue
  - Insert all the children of the node into the queue.
  - Pop the front node from the queue



Output: 6, 4, 12, 2, 5, 20, 3



# Breadth-first traversal



**BFS Algo (store output in a vector: result):**

- Create an empty **queue**.
- Create an empty **vector** called **result**.
- Insert the **root** into the **queue**.
- While queue is not empty,
  - **Append the key in the front of the queue to result**
  - Insert all the children of the node into the queue.
  - Pop the front node from the queue

**Activity 1:**

1. Trace BFS for the given tree, show how the queue evolves
2. What is the resulting vector?

# Connecting: vector and Google maps!

(PA03)

Applications: Machine Learning, Operationing Systems, Image compression, Google maps

Algorithms: BFS Task Scheduling

ADT:

Datastructure: Linked list or vector

BFS

Task Scheduling

Queue

Linked list or vector

Huffman Coding

Dijkstra's Shortest Path

Priority Queue

Binary Heap

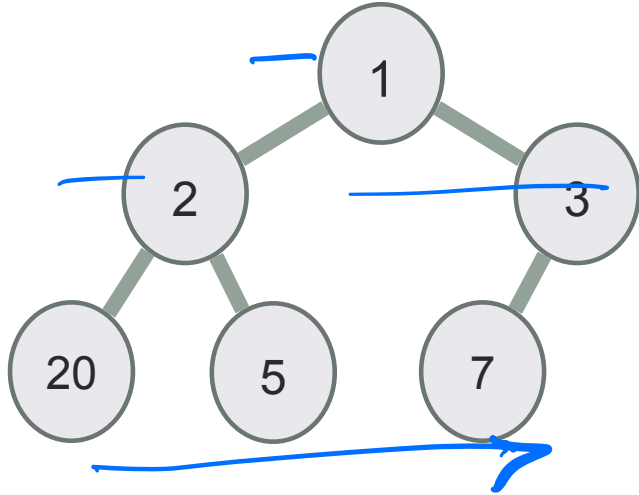
Complete Binary Tree

Vector

The priority\_queue abstract data type (ADT) is implemented as a complete binary tree.

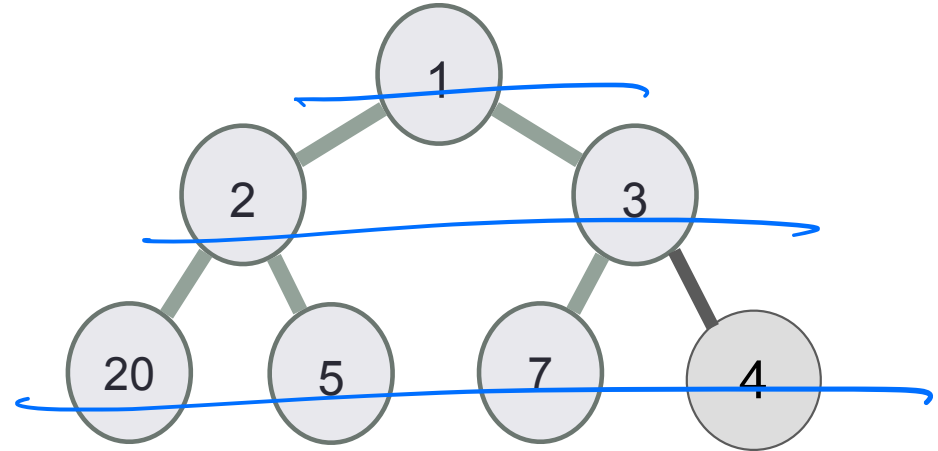
Complete binary tree is efficiently represented as a vector, by indexing keys in BFS order.

# Structure behind a priority queue



## Complete Binary Tree:

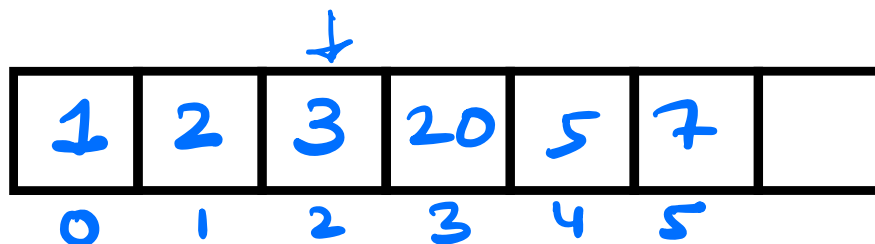
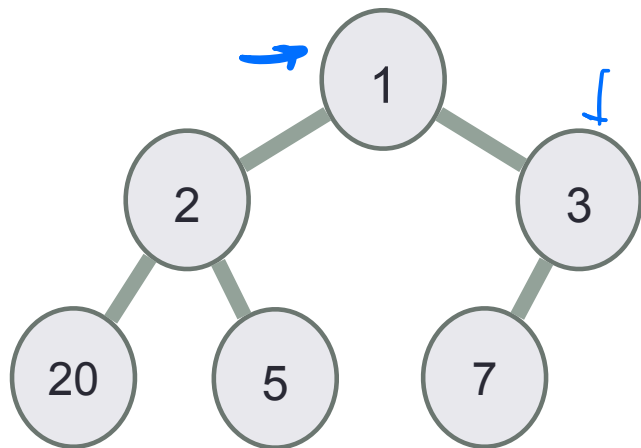
Every level is completely filled (except possibly the last level), and all nodes on the last level are as far left as possible



**Full Binary Tree:** A complete binary tree whose last level is completely filled

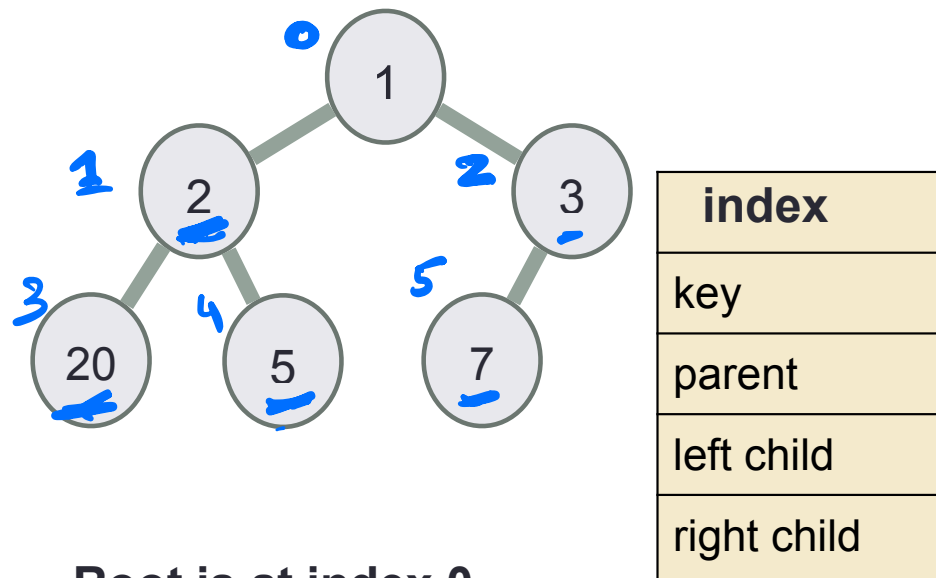
Complete/full binary trees are **balanced trees**!

# Representing a complete binary tree as a vector!



- How is the index of each key related to the index of its parent?
- How is the index of each key related to the indices of its left and right child?

# Representing a complete binary tree as a vector!



1	2	3	20	5	7	
0	1	2	3	4	5	
-1	0	0	1	1	2	
1	3	5	-	-	-	
2	4	-	-	-	-	

Root is at index 0

For a key at index  $i$ , index of its

- parent is  $\lfloor (i-1)/2 \rfloor$
- left child is  $2i+1$
- right child is  $2i+2$

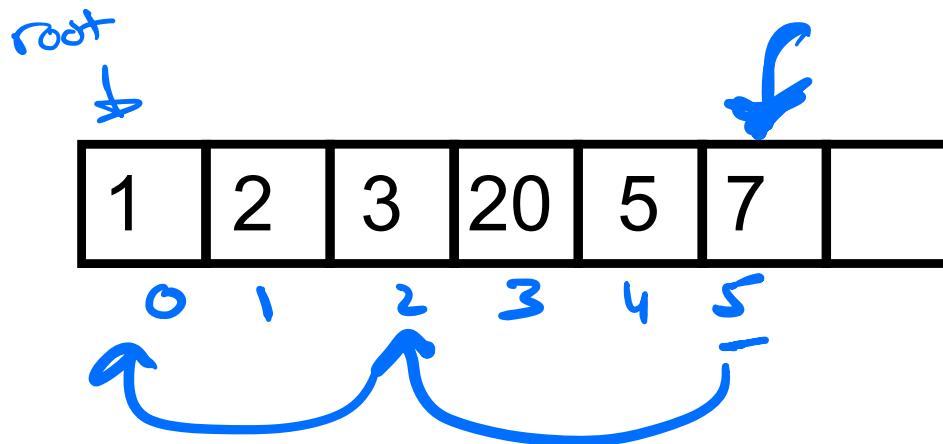
**Activity 2:** For a key at index  $i$ , determine the indices of its parent and children.

# Traverse up the tree using the vector (only)!

Root is at index 0

For a key at index  $i$ , index of its

- parent is  $\lfloor (i - 1)/2 \rfloor$
- left child is  $2i + 1$
- right child is  $2i + 2$



**Activity 3:** Starting at the last node in the last level (7), write the indices of the keys visited on the path to the root node with key (1):

A. 5, 4, 3, 2, 1, 0

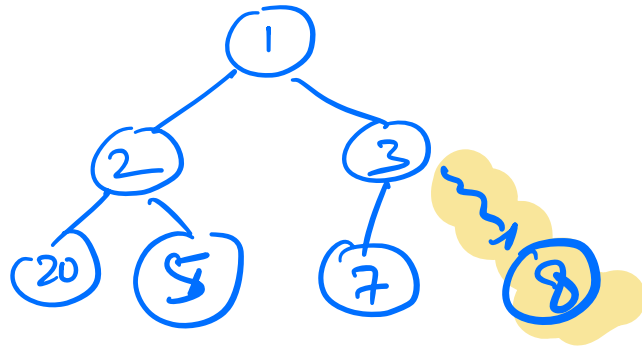
B. 5, 4, 2, 1, 0

C. 5, 3, 1

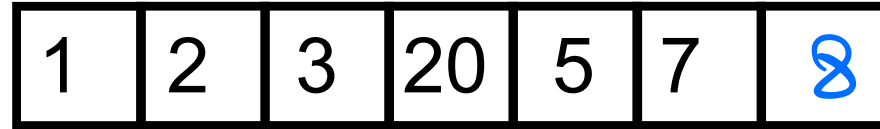
D. 5, 2, 0

E. None of the above

Add a new key with value 4 to the tree represented by this vector



*push-back (key)*



What is the complexity of adding new keys to a complete binary tree?

- ☒ A.  $O(1)$
- ☐ B.  $O(\log n)$
- ☐ C.  $O(n)$
- ☐ D. None of the above

# Show that a complete binary tree is balanced

Defn  $h(n)$ : height of the tree has  $n$  nodes

To show:  $h(n) = O(\log n)$

For a complete tree with  $n$  keys

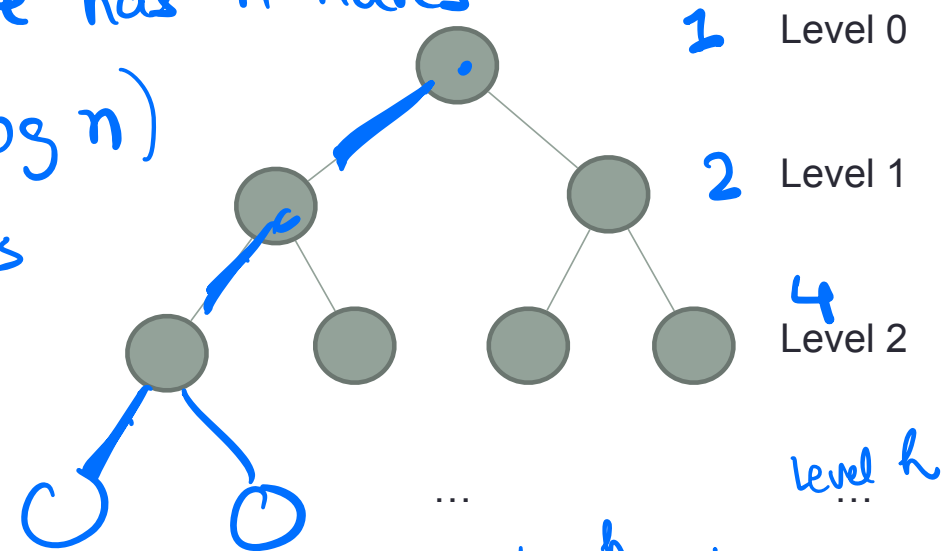
$$2^{h(n)} \leq n \leq 2^{h(n)+1} - 1$$

Taking  $\log$ :

$$h(n) \leq \log n \leq \log(n+1) \leq h(n)+1$$

Since  $h(n)$  is bounded by  $\log n$

$$h(n) = O(\log n)$$



Level  $h$  may have upto  $2^h$  nodes

Minimum number of nodes in levels 0 to  $h-1 = 2^{h-1} - 1 = 2^h - 1$

Maximum number of nodes in levels 0 to  $h = 2^{h+1} - 1$



## Related Leetcode problems to attempt in problem set 3:

- Level Order Traversal of Binary Tree (medium): <<https://leetcode.com/problems/binary-tree-level-order-traversal/description/?envType=problem-list-v2&envId=binary-tree>>
- Binary Level Order Traversal II (medium): <<https://leetcode.com/problems/binary-tree-level-order-traversal-ii/description/?envType=problem-list-v2&envId=binary-tree>>