

# RUNNING TIME ANALYSIS OF BINARY SEARCH TREES

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Problem Solving with Computers-II

The image shows the C++ logo in blue, followed by a snippet of C++ code in a monospaced font. The code is: 

```
#include <iostream>
using namespace std;
int main(){
    cout<<"Hola Facebook\n";
    return 0;
}
```

# How is PA02 going?

- A. Done!
- B. On track to finish
- C. On track to finish but my code is a mess
- D. Stuck and struggling
- E. Haven't started

# Midterm – Monday 2/25

- Cumulative but the focus will be on
  - BST
  - running time analysis
  - use of the C++ STL

# Review Big O

- What does  $f(n) = O(g(n))$  really mean?

# Binary Search Trees

- WHAT are the operations supported?
- HOW do we implement them?
- WHAT are the (worst case) running times of each operation?

Visualize BST operations: <https://visualgo.net/bn/bst>

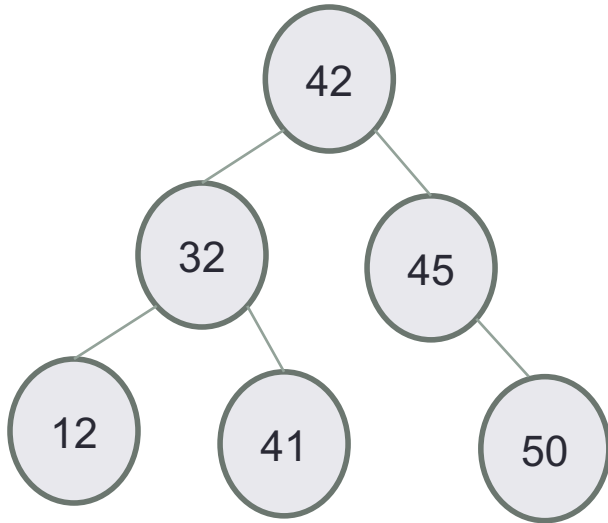
## Height of the tree



Many different BSTs are possible for the same set of keys  
Examples for keys: 12, 32, 41, 42, 45

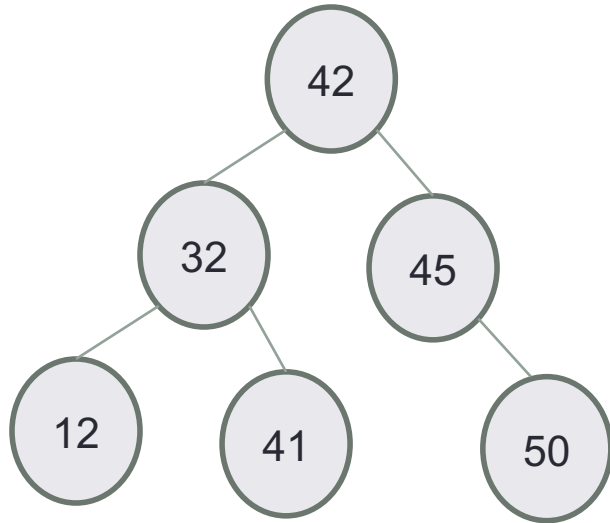
- Path – a sequence of nodes and edges connecting a node with a descendant.
- A path starts from a node and ends at another node or a leaf
- Height of node – The height of a node is the number of edges on the longest downward path between that node and a leaf.

# Worst case Big-O of search



- Given a BST of height  $H$  and  $N$  nodes, what is the worst case complexity of searching for a key?
- A.  $O(1)$
  - B.  $O(\log N)$
  - C.  $O(H)$
  - D.  $O(\log H)$

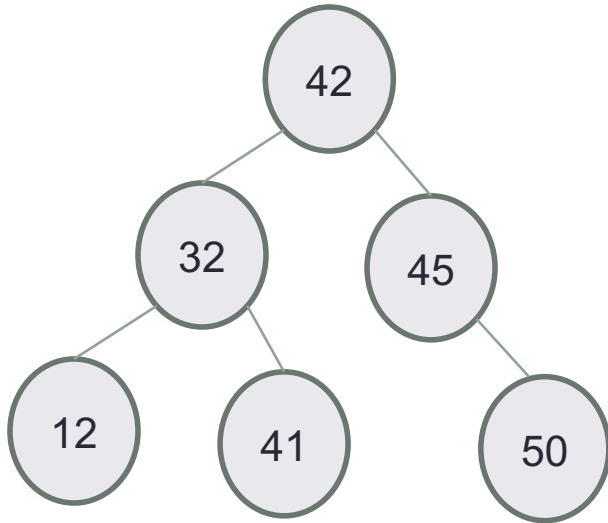
# Worst case Big-O of insert



- Given a BST of height  $H$  and  $N$  nodes, what is the worst case complexity of inserting a key?
- A.  $O(1)$
  - B.  $O(\log N)$
  - C.  $O(H)$
  - D.  $O(\log H)$

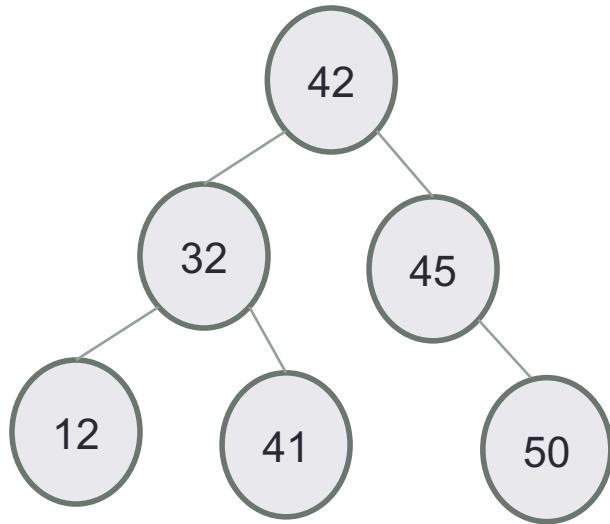


# Worst case Big-O of min/max



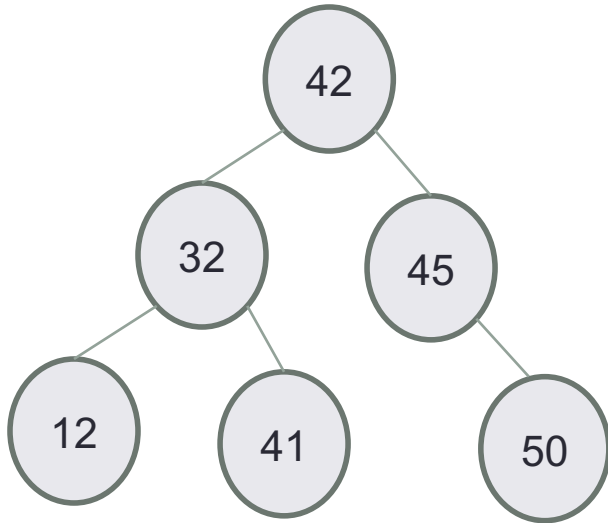
- Given a BST of height  $H$  and  $N$  nodes, what is the worst case complexity of finding the minimum or maximum key?
- A.  $O(1)$
  - B.  $O(\log N)$
  - C.  $O(H)$
  - D.  $O(\log H)$

# Worst case Big-O of predecessor/successor



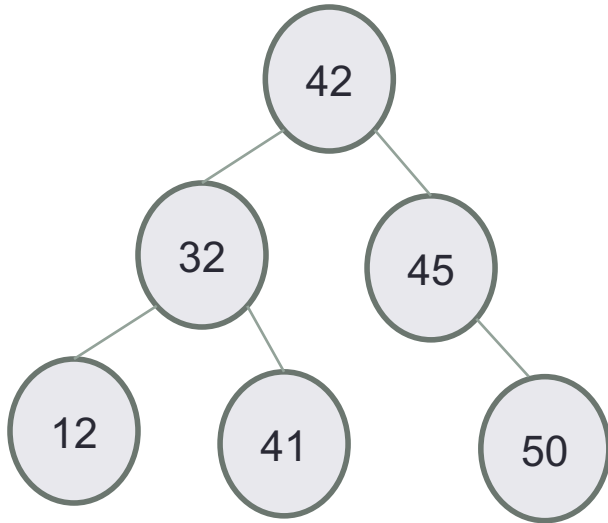
- Given a BST of height  $H$  and  $N$  nodes, what is the worst case complexity of finding the minimum or maximum key?
  - A.  $O(1)$
  - B.  $O(\log N)$
  - C.  $O(H)$
  - D.  $O(\log H)$

# Worst case Big-O of delete



- Given a BST of height  $H$  and  $N$  nodes, what is the worst case complexity of deleting the key (assume no duplicates)?
  - A.  $O(1)$
  - B.  $O(\log N)$
  - C.  $O(H)$
  - D.  $O(\log H)$

# Big O of traversals



In Order:

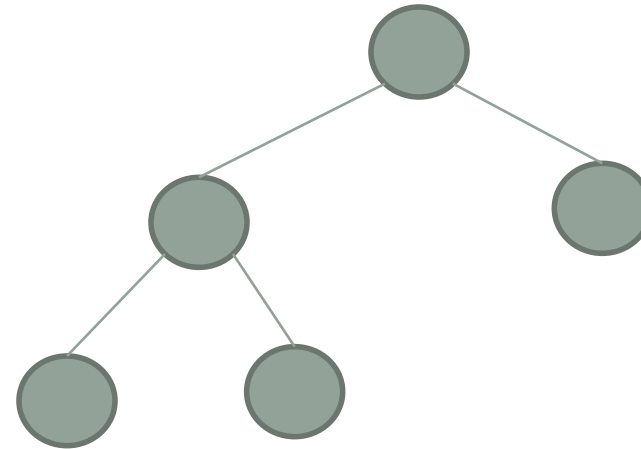
Pre Order:

Post Order:

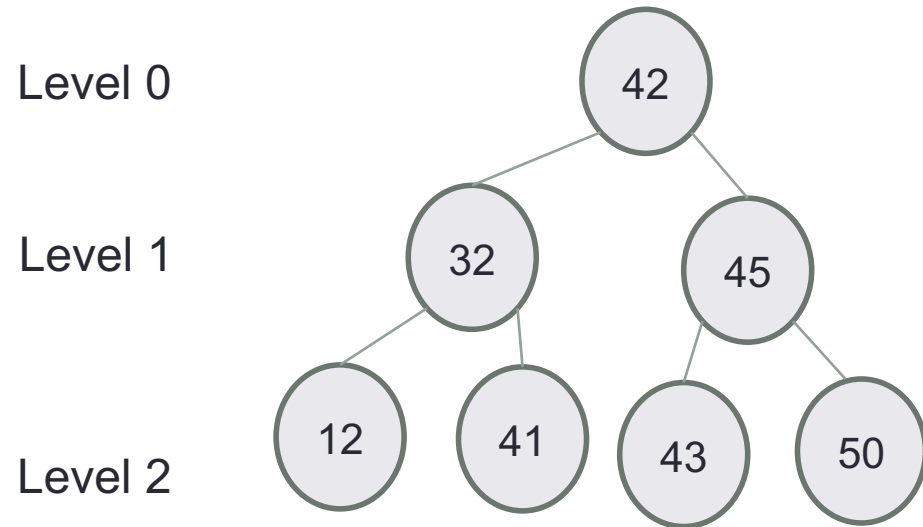
# Worst case analysis

Are binary search trees *really* faster than linked lists for finding elements?

- A. Yes
- B. No

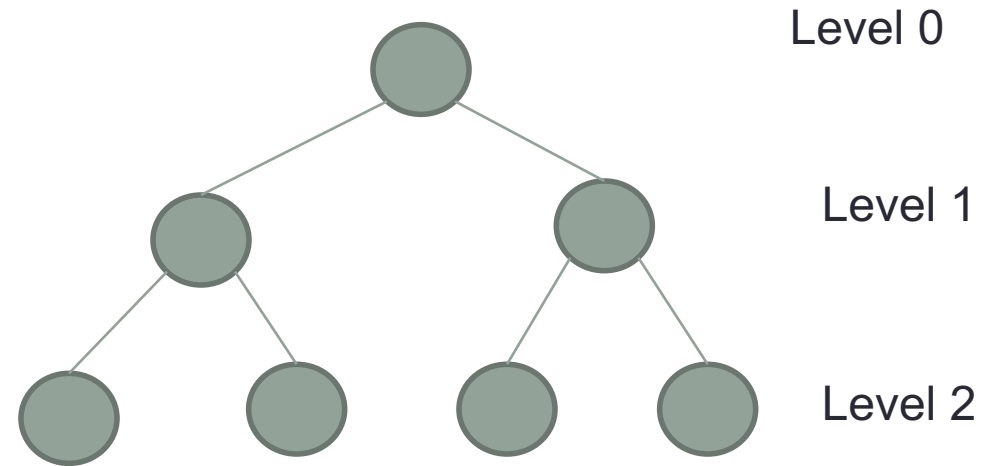


# Completely filled binary tree



Nodes at each level have exactly two children, except the nodes at the last level

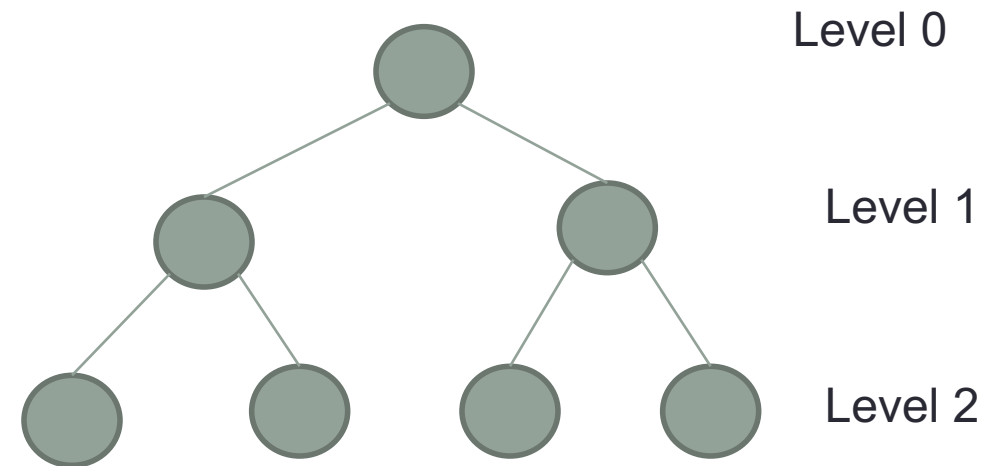
Relating  $H$  (height) and  $N$  (#nodes)  
find is  $O(H)$ , we want to find a  $f(N) = H$



How many nodes are on level  $L$  in a completely filled binary search tree?

- A. 2
- B.  $L$
- C.  $2 * L$
- D.  $2^L$

Relating  $H$  (height) and  $N$  (#nodes)  
find is  $O(H)$ , we want to find a  $f(N) = H$



Finally, what is the height (exactly) of the tree in terms of  $N$ ?



# Balanced trees

- Balanced trees by definition have a height of  $O(\log N)$
- A completely filled tree is one example of a balanced tree
- Other Balanced BSTs include AVL trees, red black trees and so on
- Visualize operations on an AVL tree: <https://visualgo.net/bn/bst>

# Summary of operations

Operation	Sorted Array	Binary Search Tree	Linked List
Min			
Max			
Median			
Successor			
Predecessor			
Search			
Insert			
Delete			

# CHANGING GEARS: C++STL

- The C++ Standard Template Library is a very handy set of three built-in components:
  - Containers: Data structures
  - Iterators: Standard way to search containers
  - Algorithms: These are what we ultimately use to solve problems

# C++ STL container classes

```
array
vector
forward_list
list
stack
queue
priority_queue
set
multiset (non unique keys)
deque
unordered_set
map
unordered_map
multimap
bitset
```