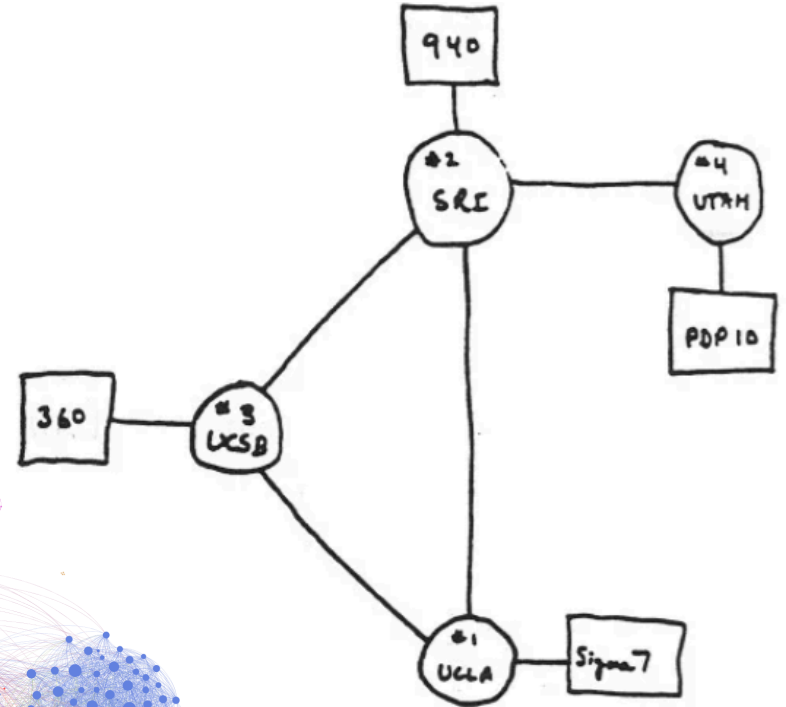
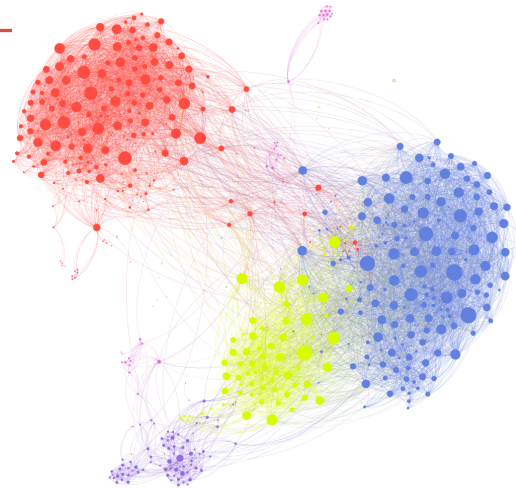
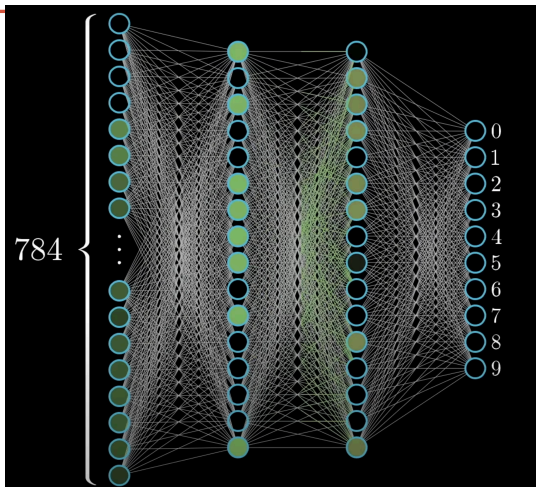


GRAPHS



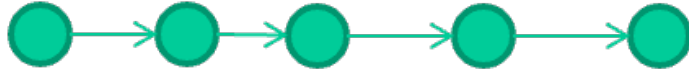
THE ARPA NETWORK

DEC 1969

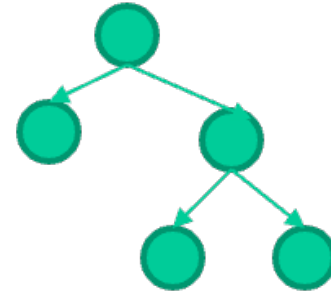
4 NODES

*The IBM 360, the IMP, and the workstations were all located in North Hall.
<https://jeweledplatypus.org/news/text/ucsbnet.html>

Kinds of data structures

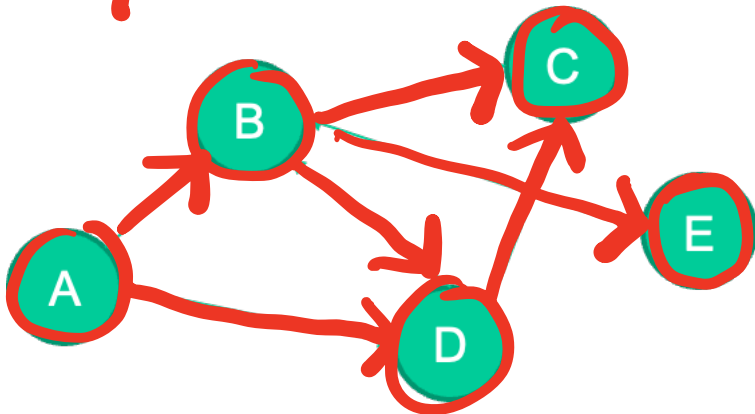


Sequential, linear structures
(arrays, linked lists)



Hierarchical structures
(trees)

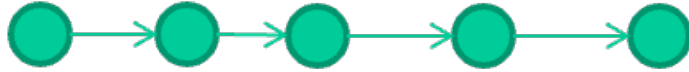
$$G = (V, E)$$



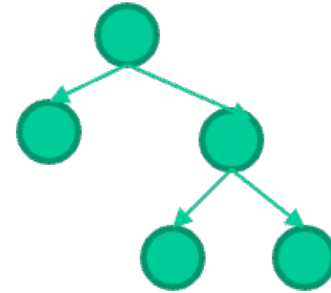
Graphs

Graphs are not hierarchical or sequential, no requirements for a “root” or “parent/child” relationships between nodes

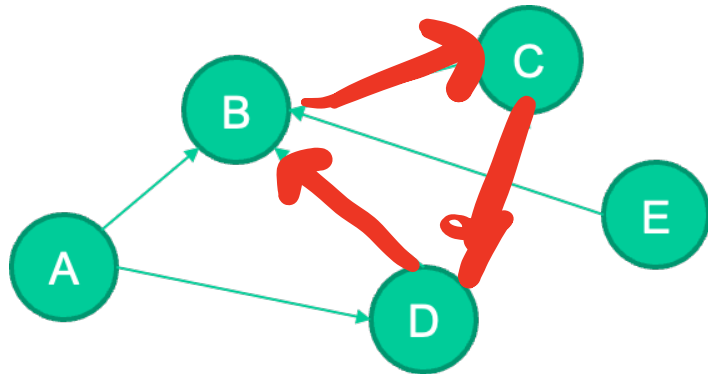
Kinds of data structures



Sequential, linear structures
(arrays, linked lists)



Hierarchical structures
(trees)



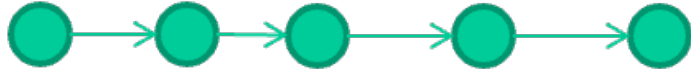
Graphs consist of

- A collection of elements (“nodes” or “vertices”)
- A set of connections (“edges” or “links” or “arcs”) between pairs of vertices.

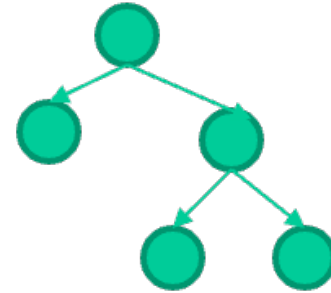
Edges may be directed or undirected

Edges may have weight associated with them

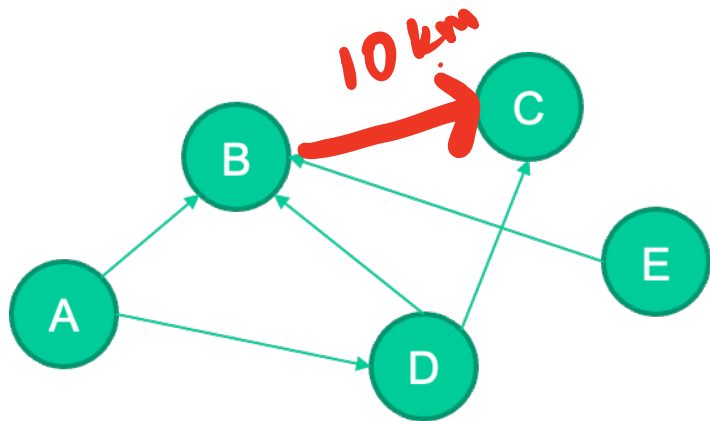
Kinds of data structures



Sequential, linear structures
(arrays, linked lists)



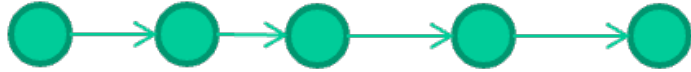
Hierarchical structures
(trees)



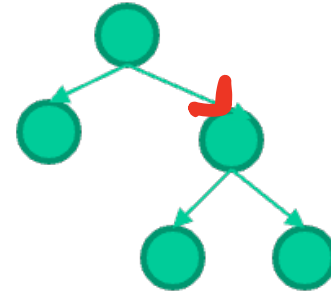
Graphs

- They consist of both vertices and edges
- They do NOT have an inherent order
- Edges may be weighed or unweighed
- Edges may be directed or undirected
- They may contain cycles

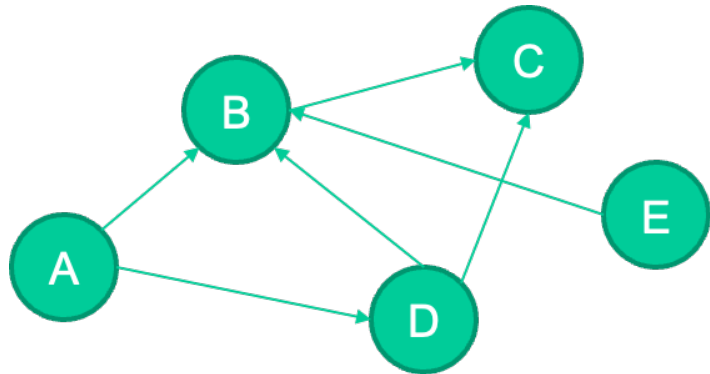
Kinds of data structures



Sequential, linear structures
(arrays, linked lists)



Hierarchical structures
(trees)

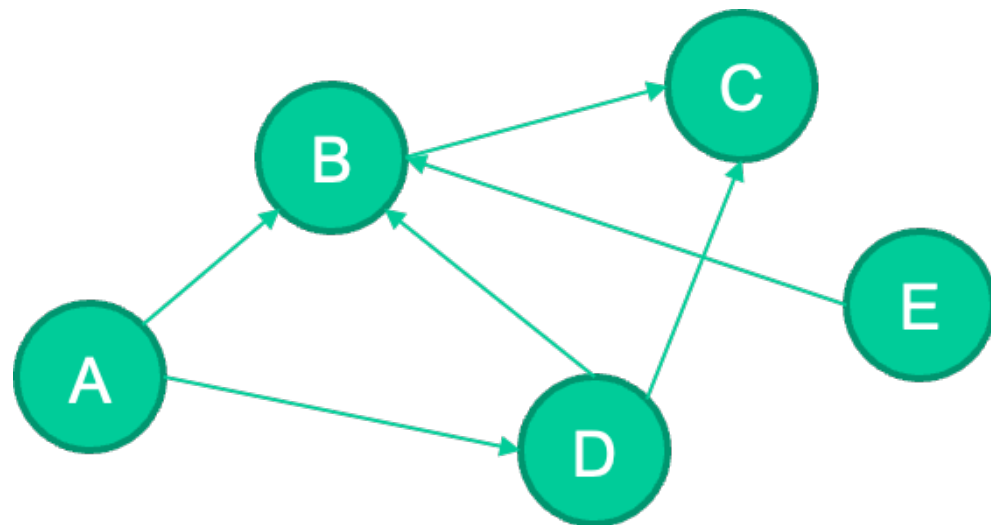


Graphs

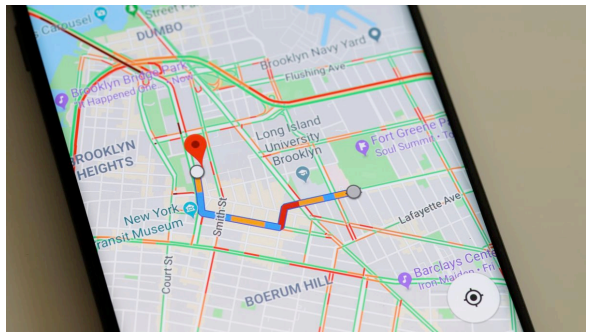
Which of the following is true about graphs?

- A. A graph can always be represented as a tree
- B. A tree can always be represented as a graph
- C. Both A and B
- D. Neither A or B

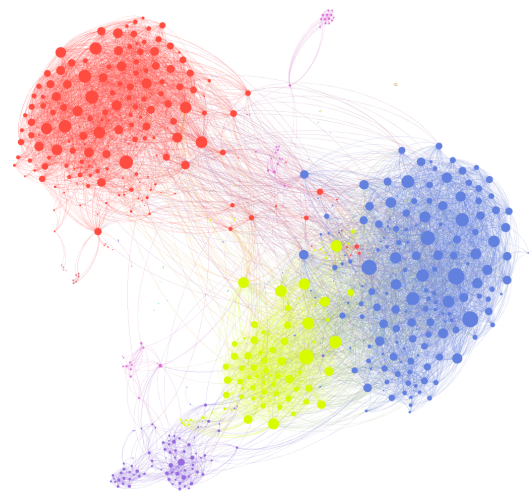
Why Graphs?



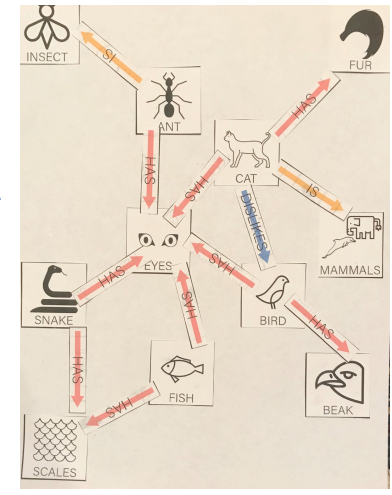
Why Graphs?



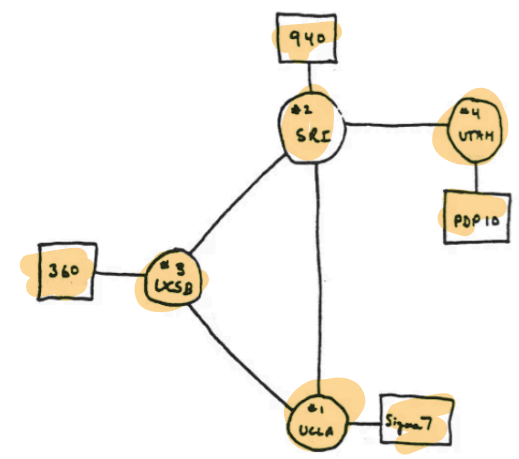
Road networks



Social networks



Semantic networks



THE ARPA NETWORK

DEC 1969

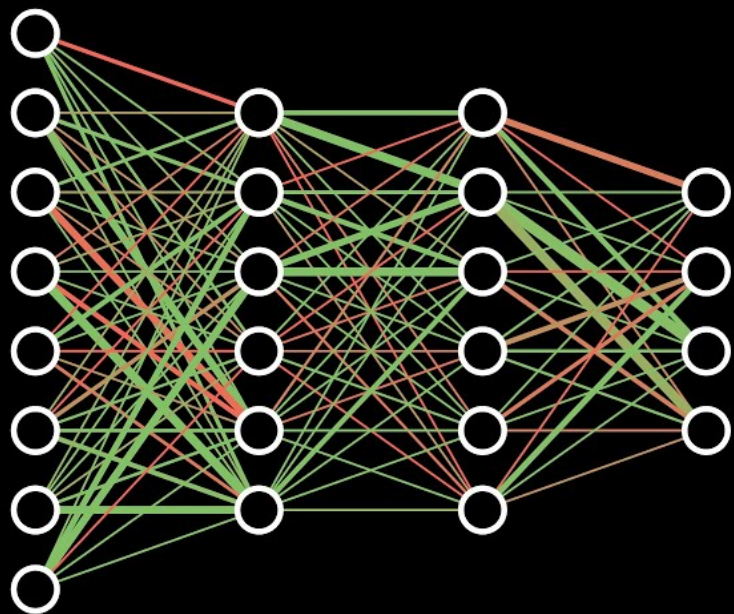
4 NODES

Computer networks

Remember: If you can map your problem to a well-known graph problem, it usually means you can solve it fast!

Next assignment: Graph applications to Machine Learning

Neural Networks



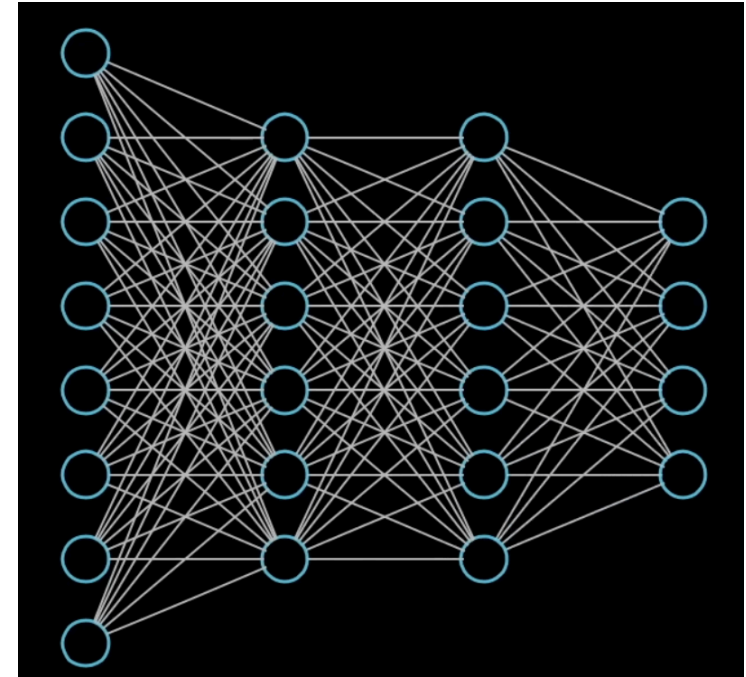
From the
ground up

<https://youtu.be/aircAruvnKk?feature=shared>

We'll listen to the first 5 minutes

In a graph representing a neural network, which of the following is FALSE? Discuss why in each case.

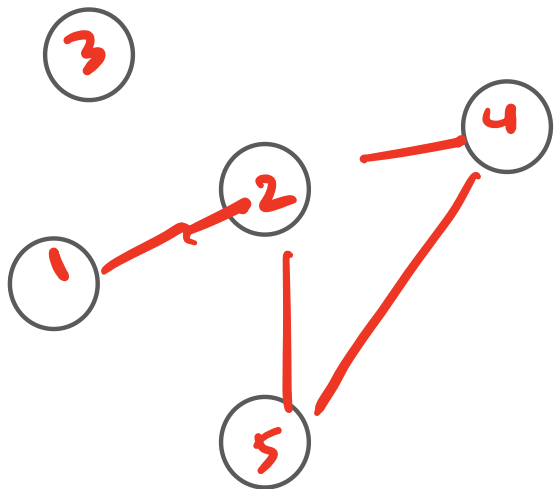
- A. Vertices represent neurons
- B. Edges represent layers
- C. Edges are directed
- D. Edges have weights



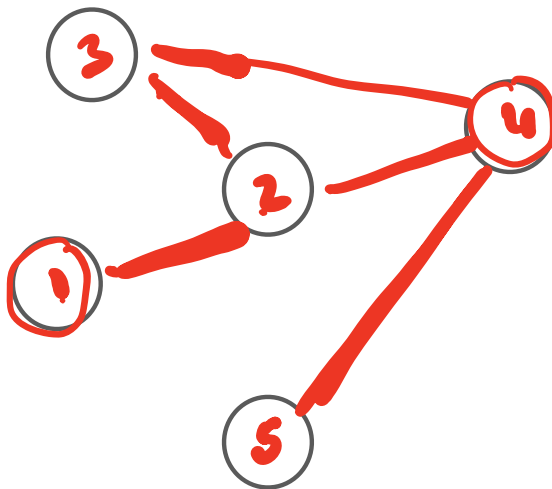
Neural Network

Types of Graphs

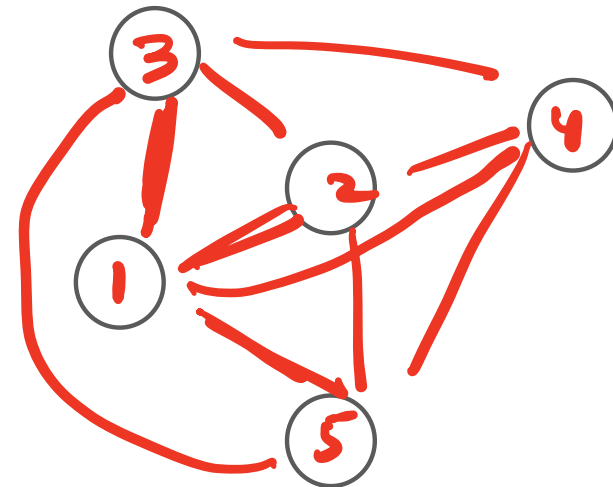
Disconnected



Connected



Fully connected



n : no. of vertices

$$O(n) \leq m \leq O(n^2)$$

n : no. of vertices

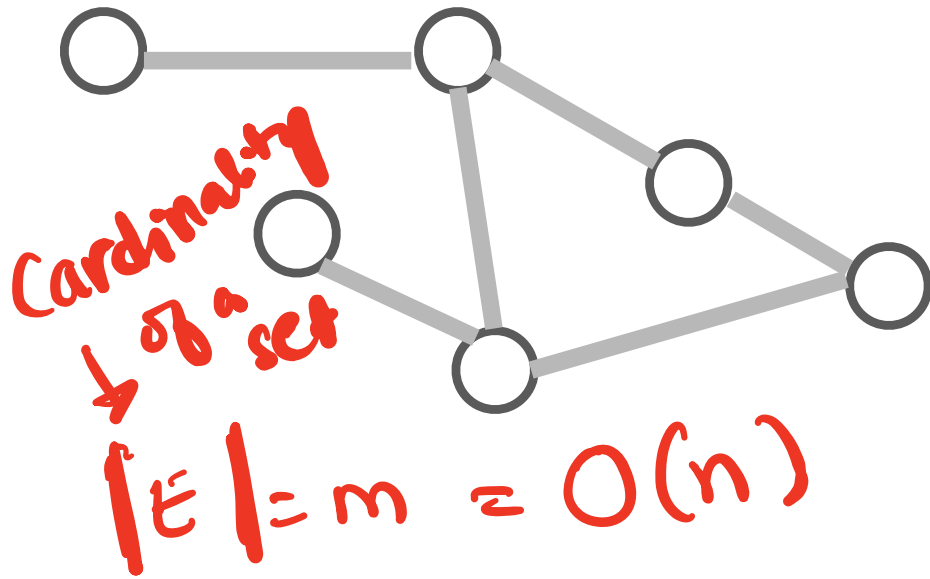
m : no. of edges

$$m = n \cdot (n-1) / 2$$

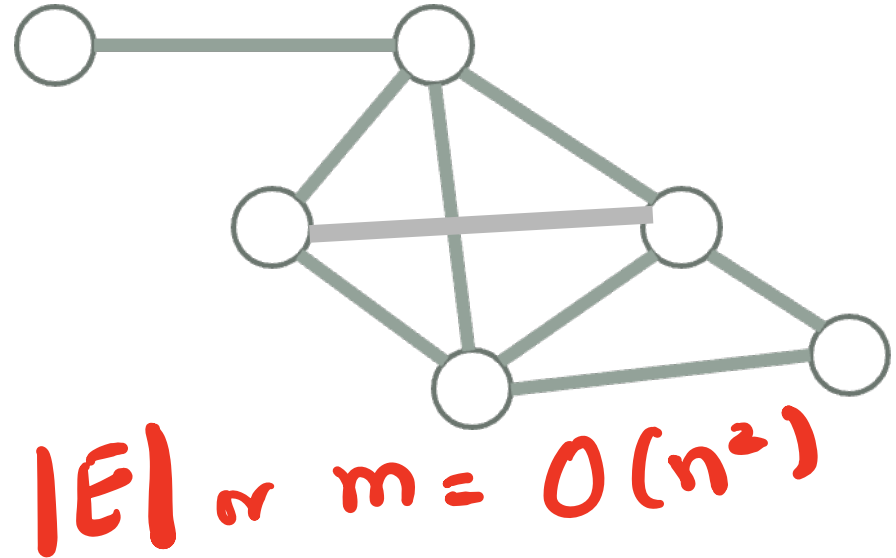
What is minimum and maximum number of edges in a connected undirected graph with n vertices (with no self-loops)?

- A. 0 and n
- B. $(n - 1)$ and $n(n - 1) / 2$
- C. $(n - 1)$ and n^2
- D. $(n - 1)$ and 2^n

Sparse vs. Dense Graphs



$$G = (V, E)$$

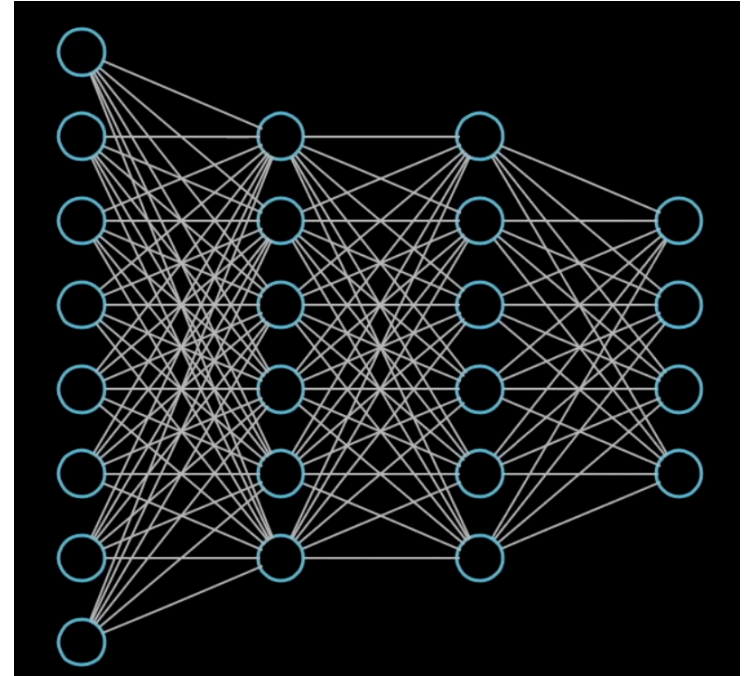


A dense graph is one where $|E|$ is “close to” $|V|^2$.

A sparse graph is one where $|E|$ is “closer to” $|V|$.

Is the neural network a sparse or dense graph?

- A. Sparse
- B. Dense
- C. Can't say!



Neural Network

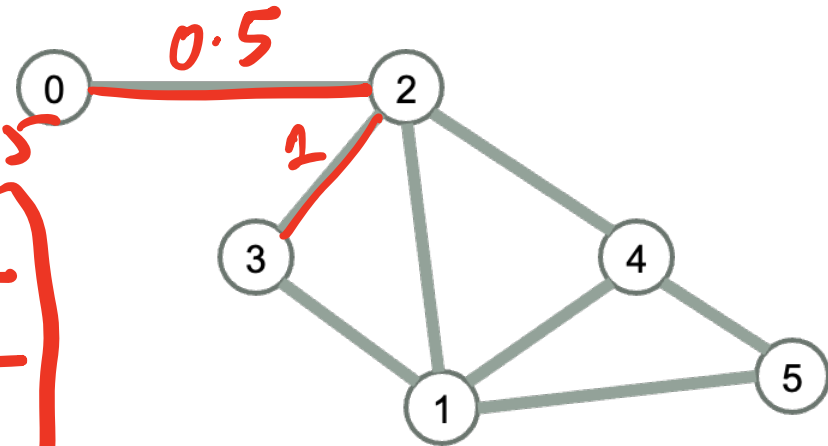
Adjacency Matrix Representation of a Graph

Represent the graph by a $n \times n$ binary/integer/float valued adjacency matrix, A

n : number of vertices or $|V|$

m : number of edges or $|E|$

	0	1	2	3	4	5
0			0.5			
1						
2	0.5			1		
3						
4						
5						

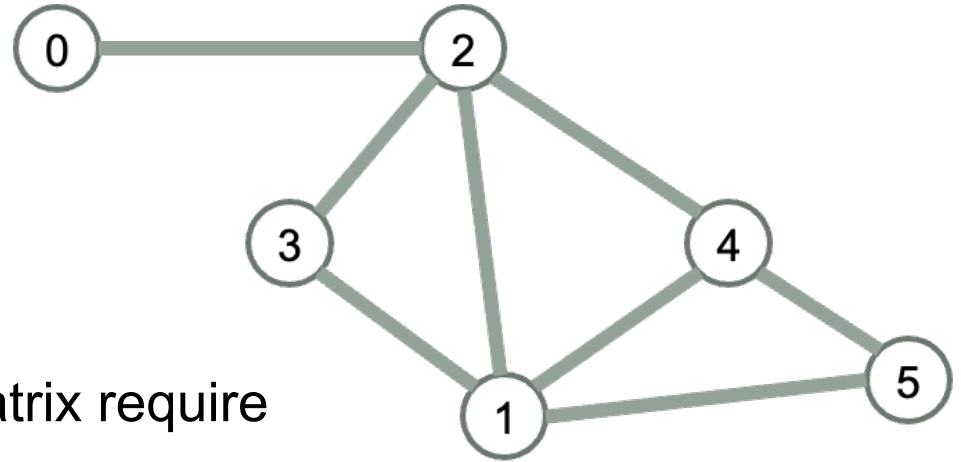


How much space does an adjacency matrix require to represent a graph?

- A. $O(n)$
- B. $O(m)$
- C. $O(n + m)$
- D. $O(n^2)$**
- E. $O(mn)$

Adjacency Matrix

Represent the graph by a $n \times n$ binary valued adjacency matrix, A
 $A[i, j] = 1$, if there is an edge from i to j



How much space does an adjacency matrix require to represent a graph?

- A. $O(n)$
- B. $O(m)$
- C. $O(n + m)$
- D. $O(n^2)$**
- E. $O(mn)$

n : number of vertices or $|V|$
 m : number of edges or $|E|$

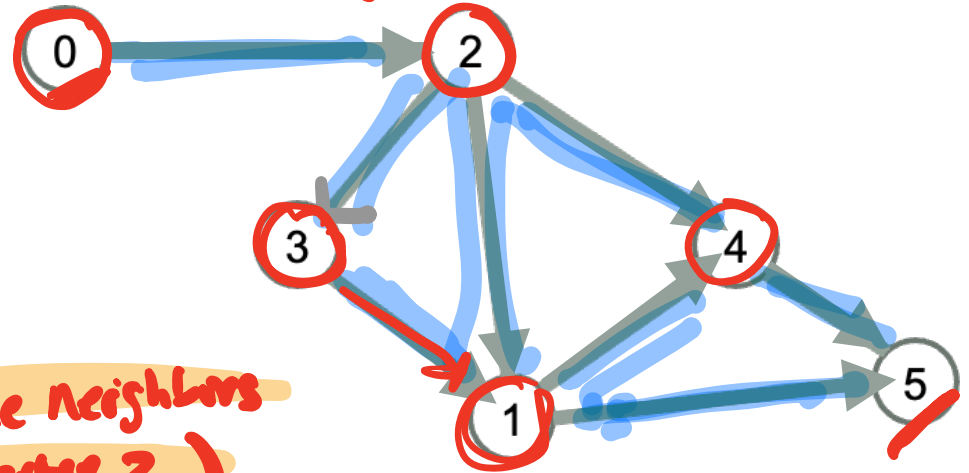
Adjacency List Representation of a Graph

- Vertices and edges stored as lists
- Each vertex points to all its edges

adjacency list

0	•	→ 2
1		→ 4 → 5
2	•	→ 3 → 1 → 4
3		→ 1
4		→ 5
5	•	

m : no. of edges n : no. of vertices



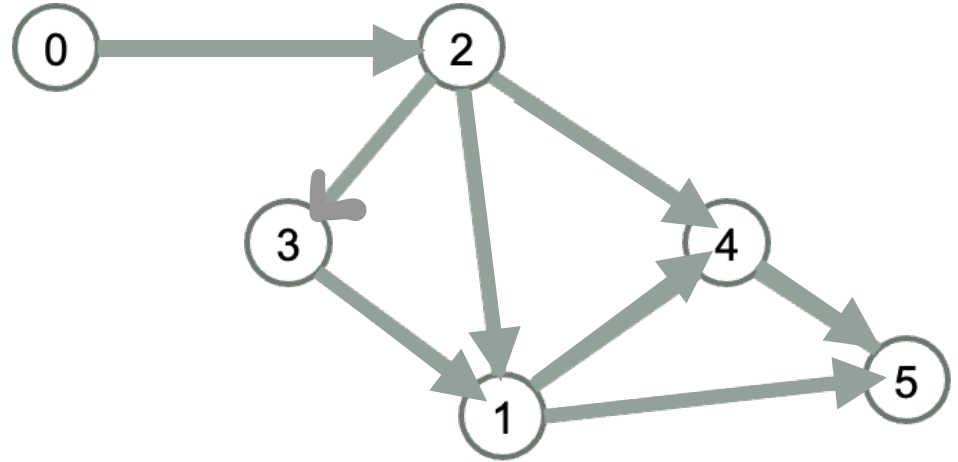
(all the neighbors of vertex 2)

How much space does an adjacency list require to represent a graph?

- $O(n)$
- $O(m)$
- $O(n + m)$ ←
- $O(n^2)$
- $O(m.n)$

Assume each vertex has a unique id between 0 and 5

```
class graph{
private:
    _____ adjlist;
};
```



Choose the ADT to represent the adjacency list

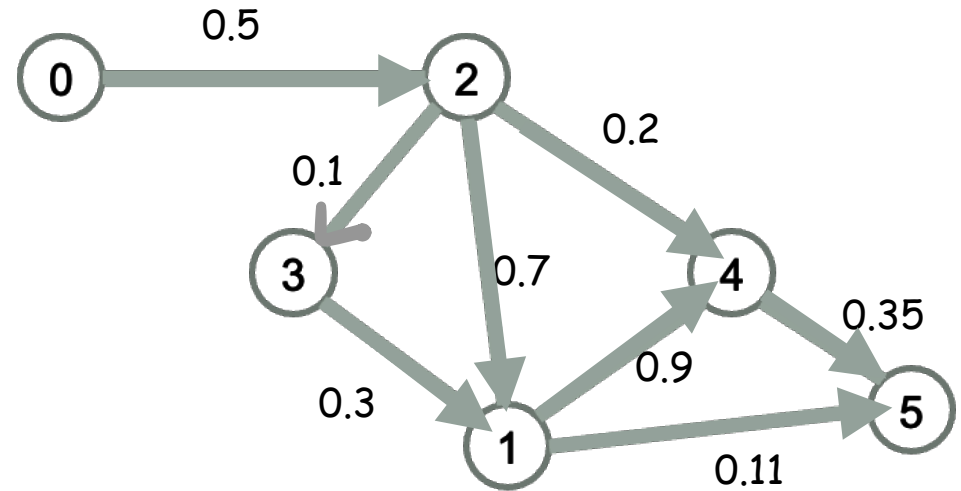
- A. vector<int> **X**
- (B)** vector<unordered_set<int>>
- C. list<vector<int>> *not a good option*
- (D)** vector<list<int>>
- E. set<list<int>> **X**

can't index into a list

Adjacency List: Weighted graph

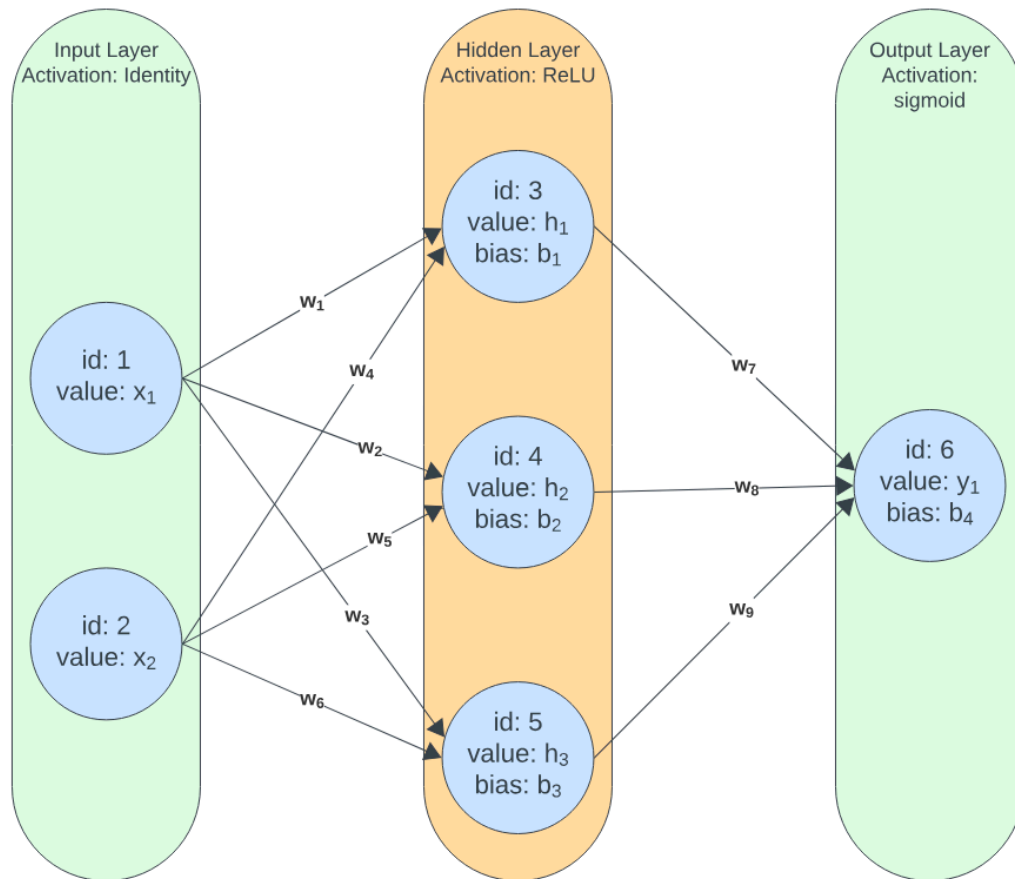
- Vertices and edges stored as lists
- Each vertex points to all its edges

0	
1	
2	
3	
4	
5	



Neural Network structure for upcoming assignment

```
typedef std::vector<std::unordered_map<int, Connection> > AdjList;
```



0	
1	
2	
3	
4	
5	

Understanding the Graph and NeuralNetwork classes

```
typedef std::vector<std::unordered_map<int, Connection> > AdjList;
```

```
class Graph {
public:
    Graph();
    Graph(int size);
    // Constructors and destructor

    // TODO: graph methods
    void updateNode(int id, NodeInfo n);
    NodeInfo* getNode(int id) const;
    void updateConnection(int v, int u, double w);

protected:
    // protected to give NeuralNetwork access

    // adjacency list containing weights for edges.
    AdjList adjacencyList;

    // vector storing node info
    std::vector<NodeInfo*> nodes;

    //Other functions
};
```

```
class NeuralNetwork : public Graph {
public:
    // Constructors and public functions

private:
    // each index of layers holds a vector which
    // contains the id's of every node in that layer.
    std::vector<std::vector<int> > layers;

    // contains ids of input nodes
    std::vector<int> inputNodeIds;

    // contains ids of output nodes
    std::vector<int> outputNodeIds;

    // since NeuralNetwork inherits from Graph, you can imagine
    // all of the graph members here as well...

};
```



```
void test_algorithm() {
    cout << "test_algorithm" << endl;
    NeuralNetwork nn(6);

    NodeInfo n0("ReLU", 0, -0.2);
    NodeInfo n1("ReLU", 0, 0.2);
    NodeInfo n2("identity", 0, 0);
    NodeInfo n3("sigmoid", 0, 0.98);
    NodeInfo n4("ReLU", 0, 0.11);
    NodeInfo n5("identity", 0, 0);

    nn.updateNode(0, n0);
    nn.updateNode(1, n1);
    nn.updateNode(2, n2);
    nn.updateNode(3, n3);
    nn.updateNode(4, n4);
    nn.updateNode(5, n5);

    nn.updateConnection(2, 1, 0.1);
    nn.updateConnection(2, 4, 0.2);
    nn.updateConnection(2, 0, 0.3);
    nn.updateConnection(5, 1, 0.4);
    nn.updateConnection(5, 4, 0.5);
    nn.updateConnection(5, 0, 0.6);
    nn.updateConnection(1, 3, 0.7);
    nn.updateConnection(4, 3, 0.8);
    nn.updateConnection(0, 3, 0.9);

    nn.setInputNodeIds({2, 5});
    nn.setOutputNodeIds({3});
}
```

Activity: Draw the final NN by hand

Next, map out the information stored in:

- `nn.nodes`
- `nn.adjacencyList`
- `nn.inputNodeIds`
- `nn.outputNodeIds`