

DIVIDE AND CONQUER: MERGESORT

Link to practice handout

<https://bit.ly/Divide-and-Conquer-Practice>

Divide and Conquer Algorithms

Algorithm Approach:

- **Divide** a large problem into sub-problems
- **Solve** each sub-problem
- **Combine** the solutions of sub-problems to obtain the solution for the original problem

Merge Sort Algorithm

`MergeSort(vector v)`

- `Divide v into left half and right half`
- `Sort the left half, then sort the right half`
- `Combine (merge) the two sorted halves`

Example run of
mergesort

[7 2]

[7 2 3 -1]

Example run of
mergesort

[7 2 5 3 -1]

Activity 1: Trace merge sort on the above example input with 5 elements
Draw the final binary tree representation of the trace.
What is the height of the resulting binary tree?

[7 2 5 3 -1]

[7 2] [5 3 -1]

[7] [2] [5] [3 -1]

 [3] [-1]

Running Time Analysis

$T(n) = \# \text{ copy operations to split lists} +$
 $\# \text{ comparisons to merge lists} +$
 $\# \text{ function calls}$

[7 2 5 3 -1]

[7 2] [5 3 -1]

[7] [2] [5] [3 -1]

 [3] [-1]

Space Complexity Analysis

How much additional space is used by the time mergesort reaches the base case?

A. $n \cdot \log(n)$

B. $n + n/2 + n/4 + n/8 + \dots + 1$

C. $n + n/2 + n/4 + n/8 + \dots + 1 + \log(n)$

D. Something else

Heap Sort



Source: <https://cosmictechie.hashnode.dev/heap-sort>

HeapSort Algorithm

HeapSort(vector v)

```
for i from n/2-1 down to 0: // heapify: build max heap
    bubble_down(v, n, i)

for i from n-1 down to 1: // sort invariant:
    swap(v[0], v[i])      heap: v[0..i-1]
    bubble_down(v, i, 0)  sorted: v[i..n-1]
```

Heapsort: <https://visualgo.net/en/heap>

Why Mergesort over Heapsort?

- Same $O(n \log n)$ time, but heapsort has poor cache performance - why?
- Mergesort is **stable**: equal elements keep their original relative order
- Mergesort parallelizes naturally