

DIVIDE AND CONQUER: MERGESORT

Link to practice handout

<https://bit.ly/Divide-and-Conquer-Practice>

Divide and Conquer Algorithms

Algorithm Approach:

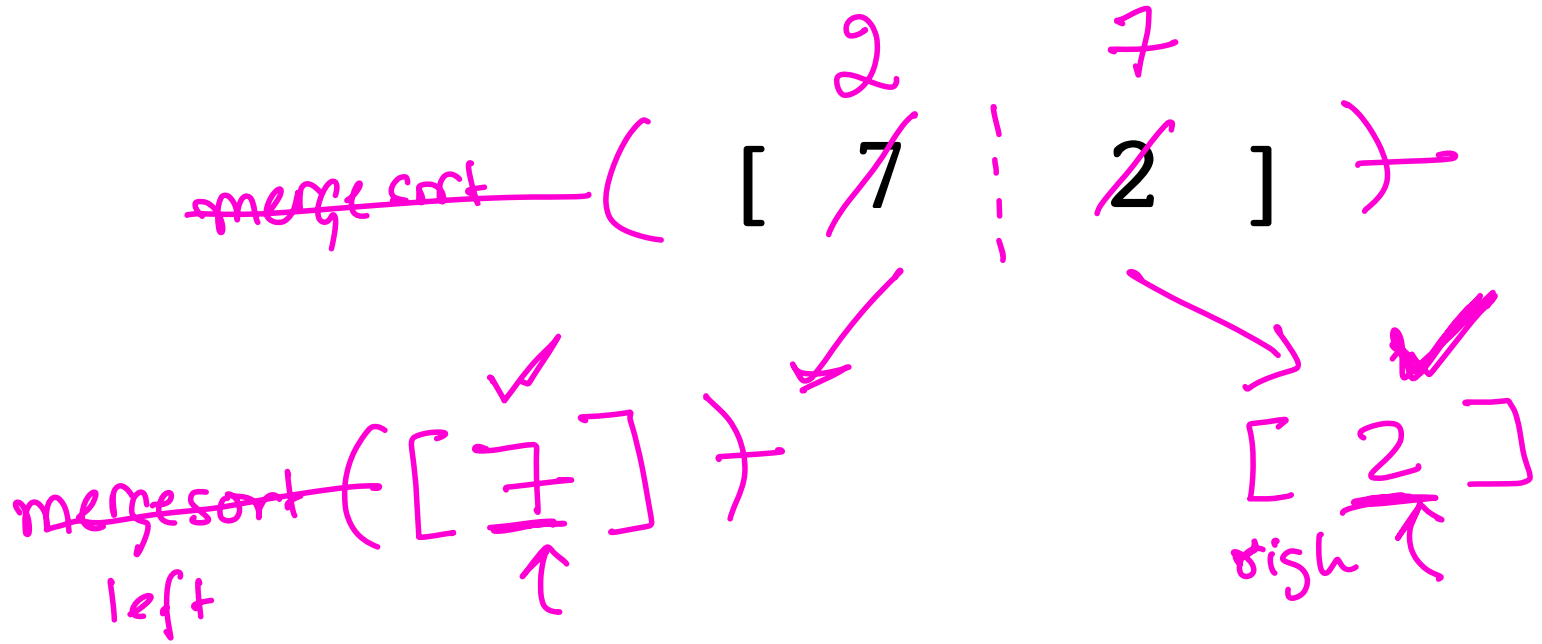
- **Divide** a large problem into sub-problems
- **Solve** each sub-problem
- **Combine** the solutions of sub-problems to obtain the solution for the original problem

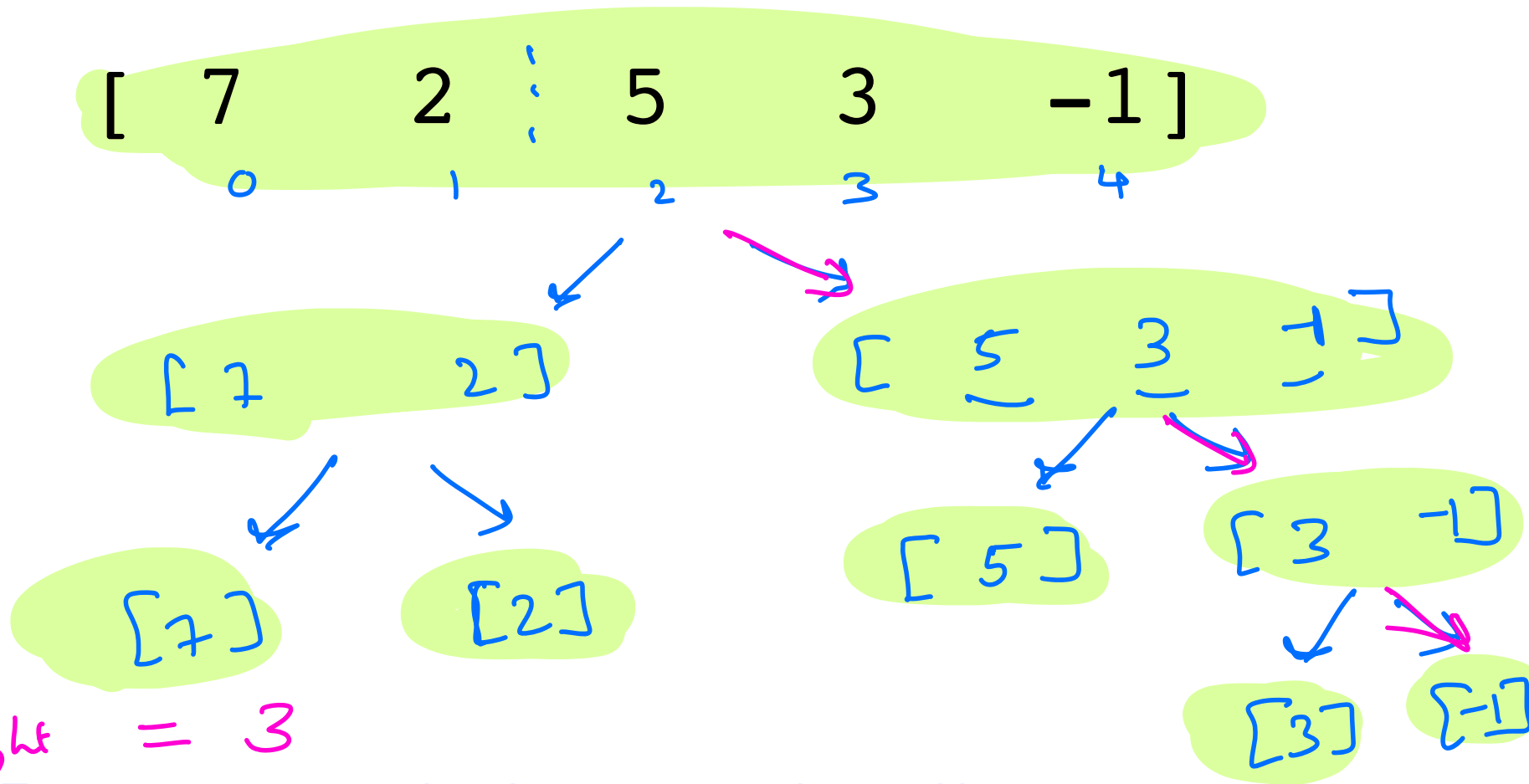
Merge Sort Algorithm

`MergeSort(vector v)`

- Divide `v` into left half and right half
- Sort the left half, then sort the right half
- Combine (merge) the two sorted halves

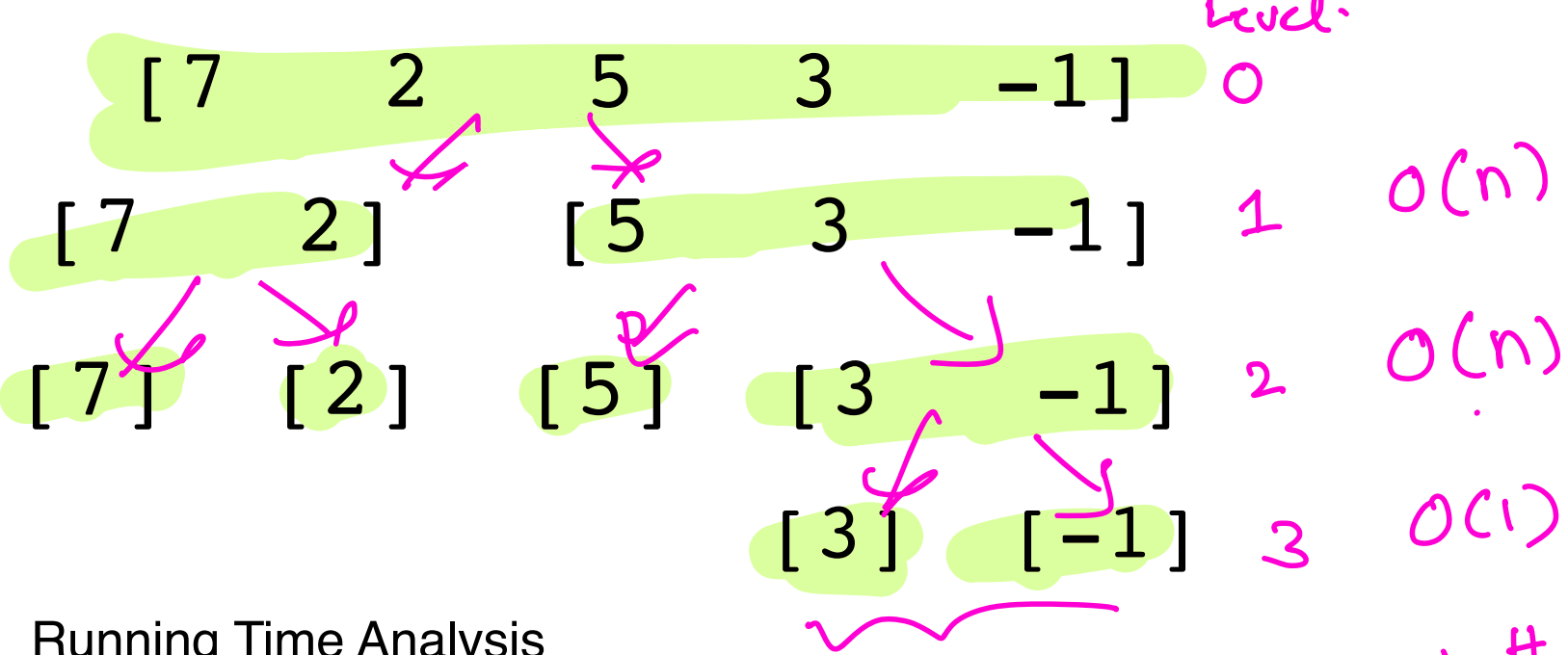
Example run of mergesort





Height = 3

Activity 1: Trace merge sort on the above example input with 5 elements
 Draw the final binary tree representation of the trace.
 What is the height of the resulting binary tree?



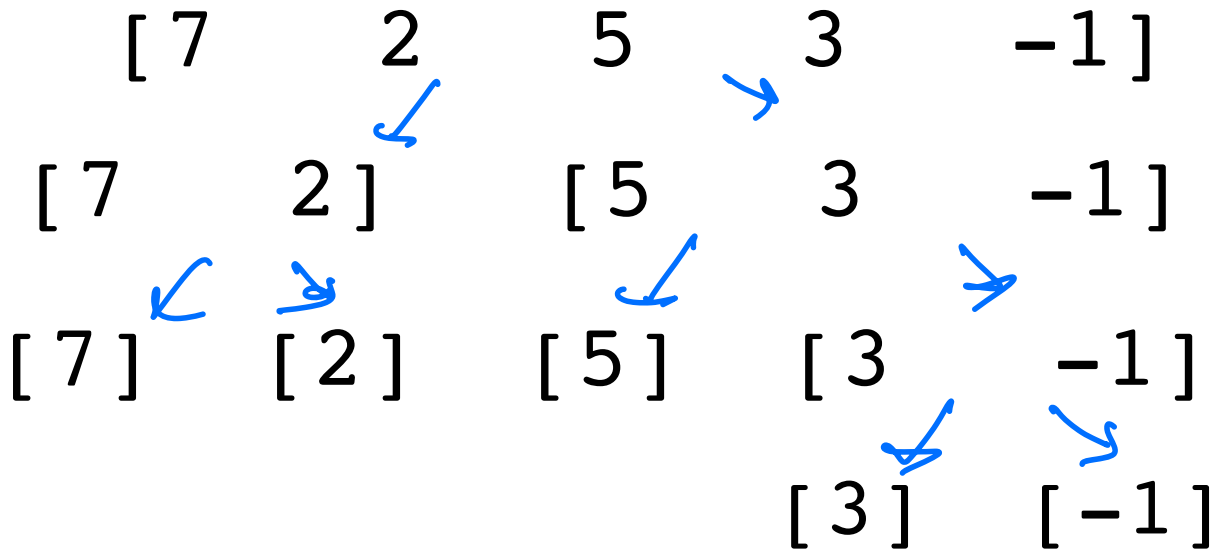
Running time
 $= \log(n) (O(n) + O(n)) + 2^{n-1}$
 $= O(n \log n)$

Running Time Analysis

$T(n) = \# \text{ copy operations to split lists} + \# \text{ comparisons to merge lists} + \# \text{ function calls}$

copy operations $\leq \log(n) \cdot O(n)$
 # comparisons to merge $\leq \log^n O(n)$

function calls
 $\leq 2^0 + 2^1 + 2^2 + \dots + 2^{n-1}$
 $= 2^{n+1} - 1$
 $= 2 \cdot 2^n - 1$
 $= 2^{n+1} - 1$



Space Complexity Analysis

How much additional space is used by the time mergesort reaches the base case?

A. $n \cdot \log(n)$

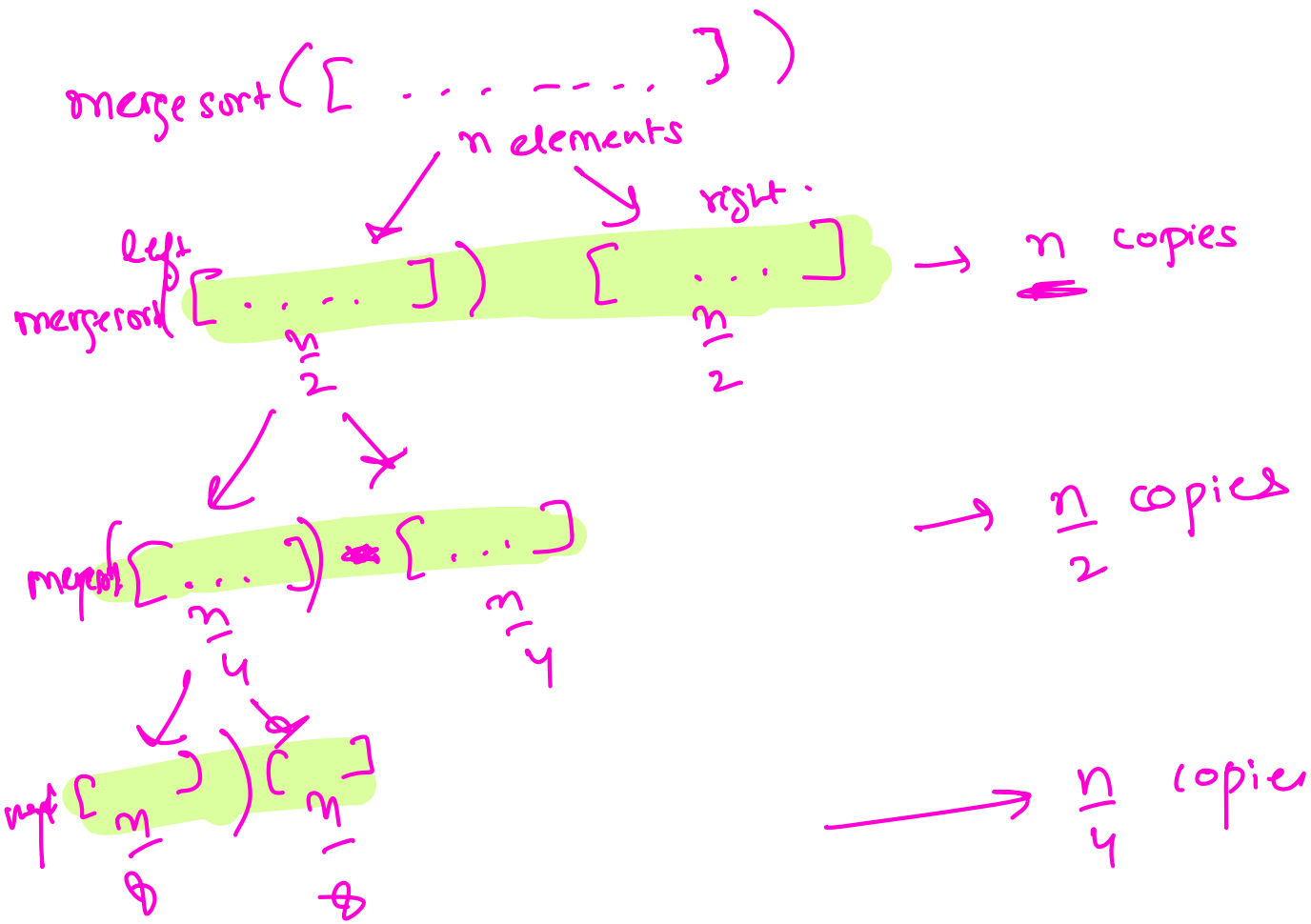
B. $n + n/2 + n/4 + n/8 + \dots + 1$

C. $n + n/2 + n/4 + n/8 + \dots + 1 + \log(n)$

D. Something else

Analysis of space complexity of mergesort.

Main insight: Not all recursive calls are active at the same time



Consider space used when the max. depth of the recursion is reached. This is the peak auxiliary space usage

$$S(n) = n + \frac{n}{2} + \frac{n}{4} + \dots + \frac{n}{n}$$

$$= n \left(1 + \frac{1}{2} + \frac{1}{4} + \frac{1}{8} + \frac{1}{16} + \dots \right)$$

Since the denominator for each term grows exponentially
the summation converges to a constant

$$S(n) = n \cdot \text{constant}$$
$$= O(n)$$

Heap Sort



Source: <https://cosmictechie.hashnode.dev/heap-sort>

HeapSort Algorithm

HeapSort(vector v)

```
for i from n/2-1 down to 0: // heapify: build max heap  
    bubble_down(v, n, i)
```

$O(n)$

```
for i from n-1 down to 1: // sort invariant:  
    swap(v[0], v[i]) // heap: v[0..i-1]  
    bubble_down(v, i, 0) // sorted: v[i..n-1]
```

$O(n \log n)$

Overall $O(n \log n)$

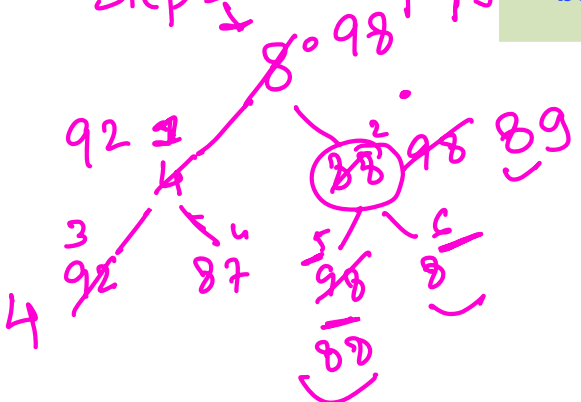
Heapsort: <https://visualgo.net/en/heap>

Trace heapsort on input vector: 8, 4, 88, 92, 87, 98, 89

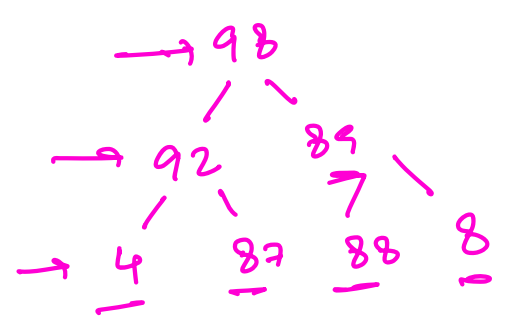
```

for i from  $n/2-1$  down to 0: // heapify: build max heap
    bubble_down(v, n, i)
    
```

Step 1: Heapify



$n = 7$ $\frac{n}{2} - 1 = 2$



Expected max-heap:

max: heap 98 92 89 4 87 88 8

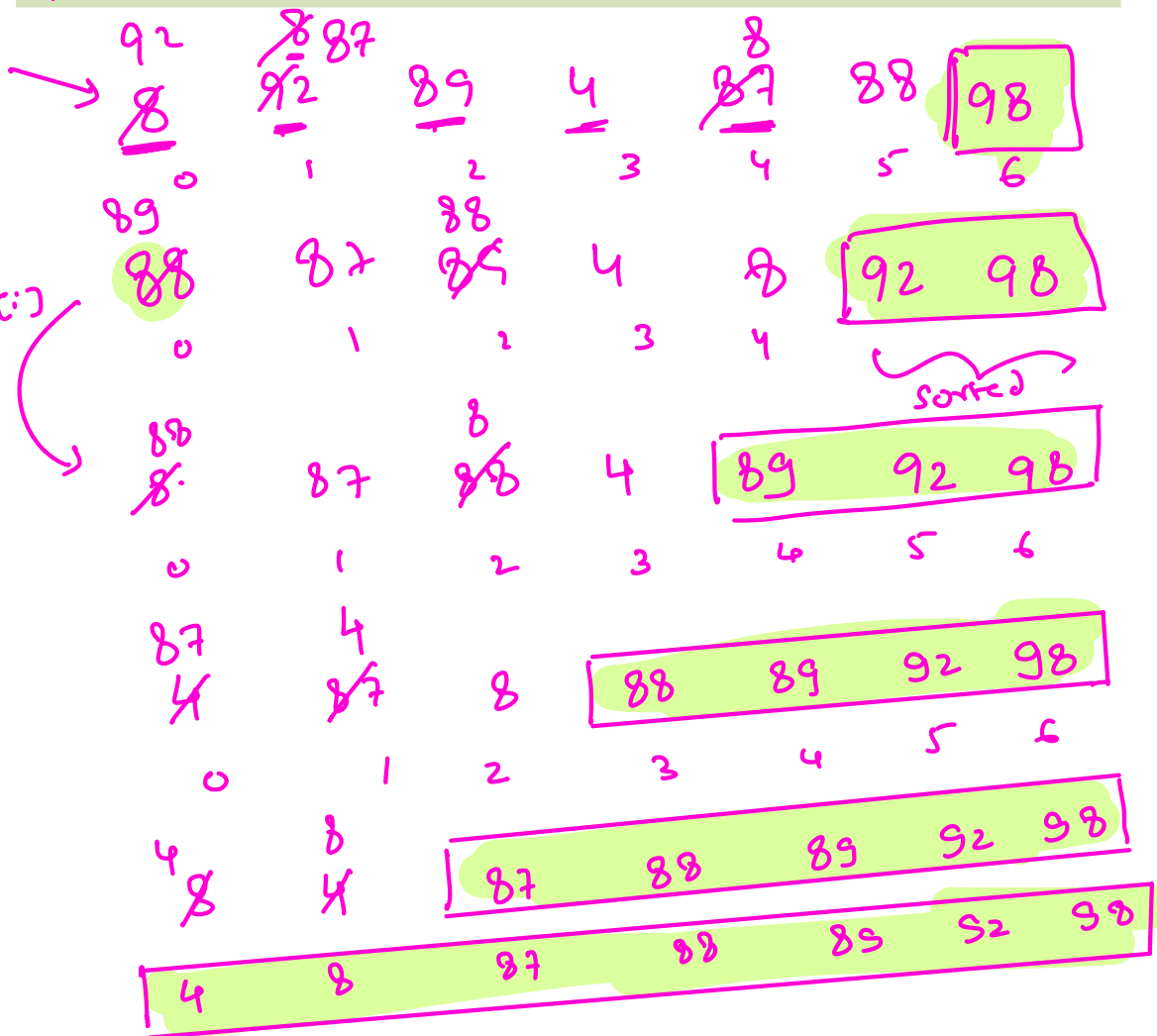
0 1 2 3 4 5 6

Step 2:

```

for i from n-1 down to 1: // sort invariant:
    swap(v[0], v[i])      heap: v[0..i-1]
    bubble_down(v, i, 0)  sorted: v[i..n-1]
    
```

Swap $v[0], v[i]$
Bubble down
to fix heap
property



Why Mergesort over Heapsort?

- Same $O(n \log n)$ time, but heapsort has poor cache performance - why?
- Mergesort is **stable**: equal elements keep their original relative order
- Mergesort parallelizes naturally